

# Remote Sensing Milestones

“US Experience”



August 04



Niranjan Vescio, ESPH  
August 12, 2004



# Presentation Outline

1. Brief intro to RSD Technology
2. History and Evolution
3. Applications & Regulations
4. Technology & Performance
  - a. Gasoline Vehicle Measurement.
    - i. Technology (HW & SW)
    - ii. Matching Laboratory Analyzers
    - iii. Matching Inspection Results
    - iv. Matching Fleet Emissions
  - b. Diesel Vehicles...Where are we?
    - i. Technology (HW & SW)
    - ii. Matching Laboratory Analyzers
    - iii. Matching Inspection Results
    - iv. Matching Fleet Emissions

# Technology Brief



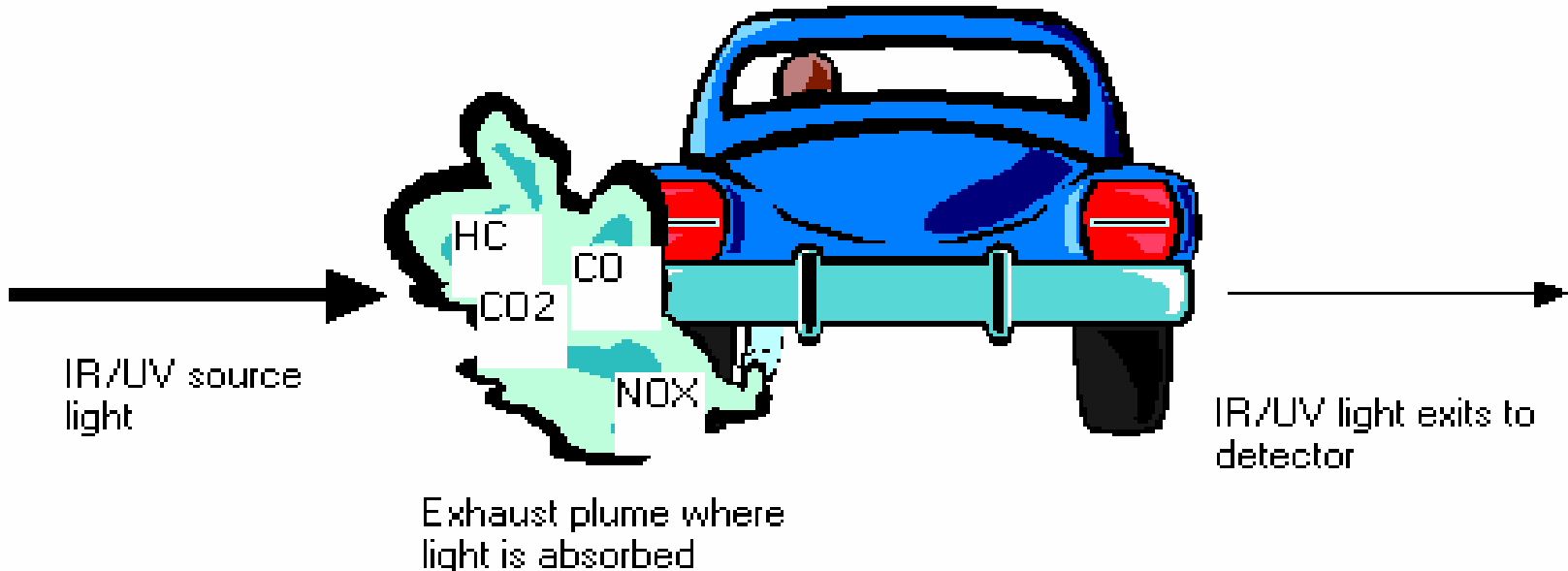
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# On-road Measurement Principle

## Spectroscopy (Light Absorption)

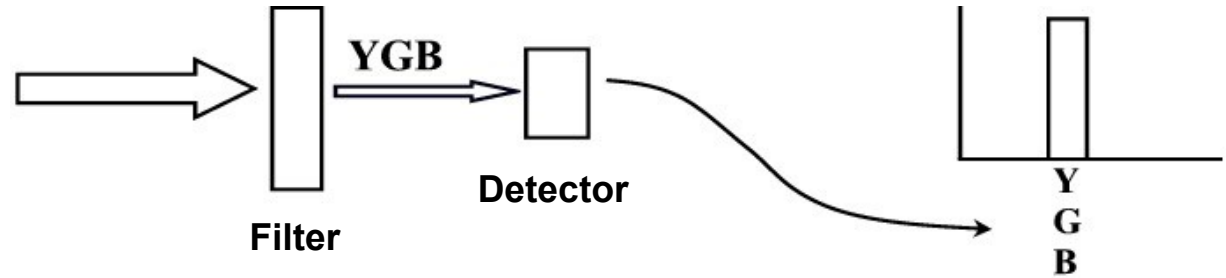




# Familiar Science

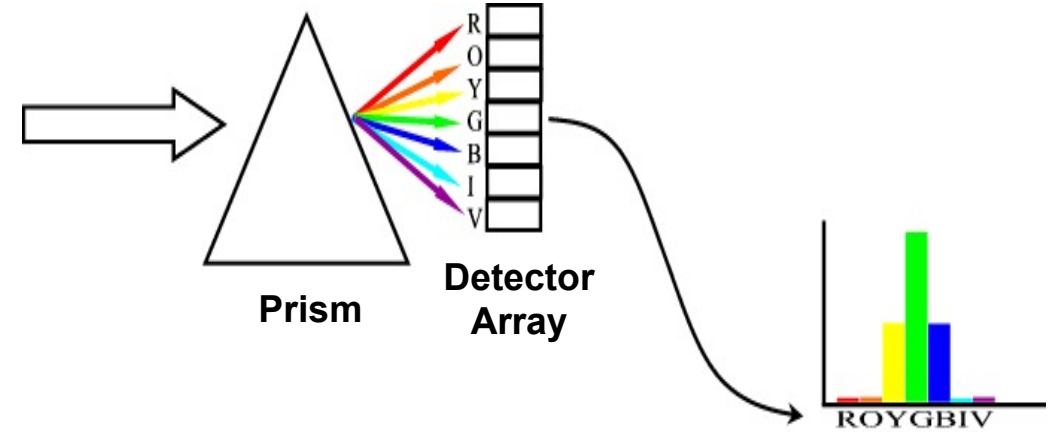
## 1. Infrared – CO, HC, CO<sub>2</sub>

### a. Non-Dispersive Infrared (NDIR)



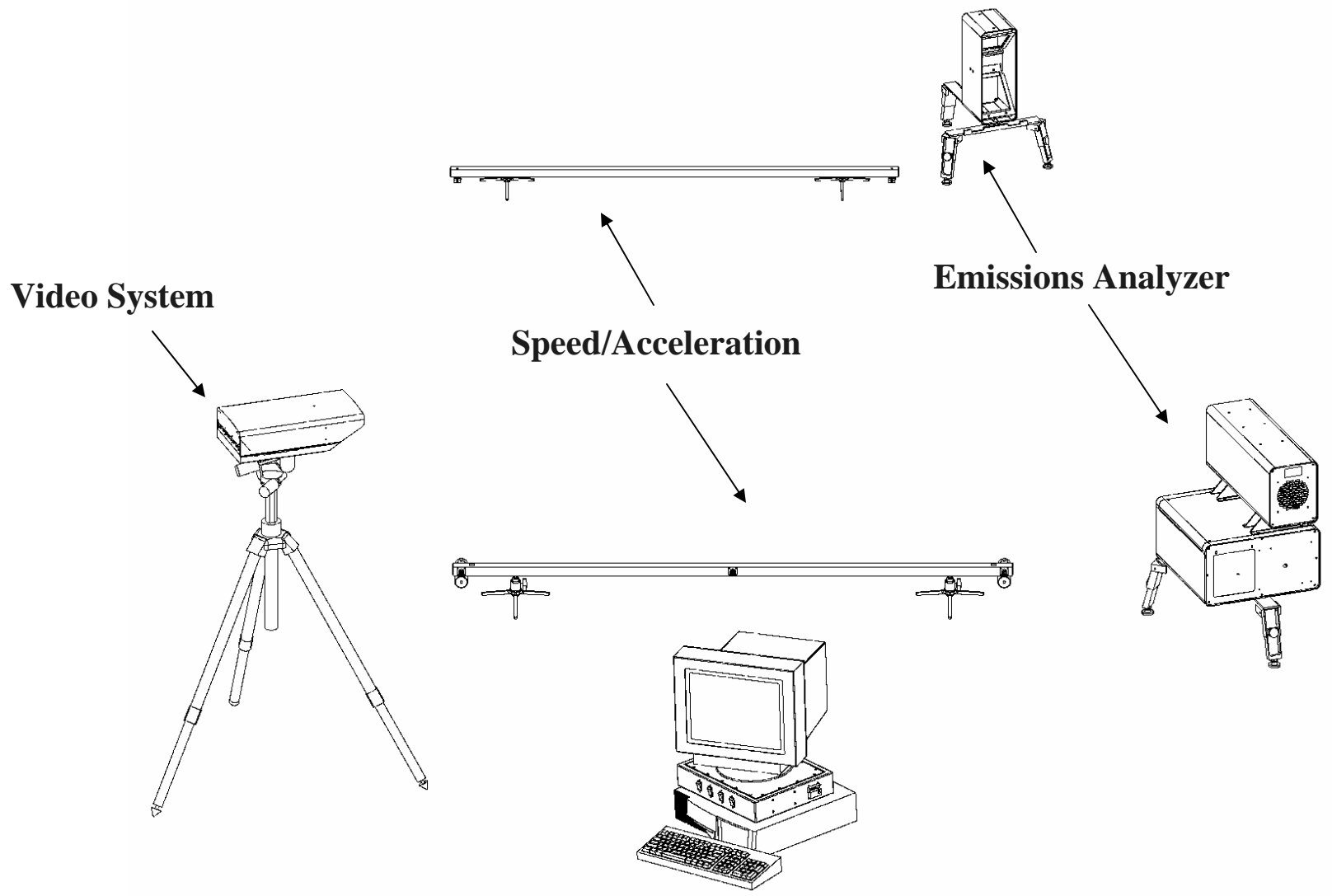
## 2. Ultraviolet – NO

### a. Dispersive Ultraviolet (DUV)





# Remote Sensing System Components





# Remote Sensing Technology

Hardware: [www.rsdaccuscan.com](http://www.rsdaccuscan.com)

The screenshot displays the RSD Accuscan software interface. On the left, a menu lists options: I - Site Information, M - Mirror Alignment, C - Calibration, S - Statistics, R - Road Testing, Y - Replay, F1 - Help, and F2 - Setting. Below the menu, a small video window shows the rear of an orange car. Real-time data is displayed below the video: SPEED = 37.5 mph, ACCELERATION = 2.5 mph/sec, CO = 0.2%, CO2 = 11.1 %, HC = 135 ppm, and NOx = 321 ppm. On the right, three yellow buttons are visible: Speed & Acceleration, Exhaust Emissions, and Camera Capturing. Below the buttons, a diagram shows a car on a road with a sensor unit and a camera mounted on a pole above it, connected by cables.

- 3 active systems collect all relevant information in less than 1 second.
- Hold the cursor above any button to highlight the components of a system
- Click for a description of system operation

Speed & Acceleration  
Exhaust Emissions  
Camera Capturing

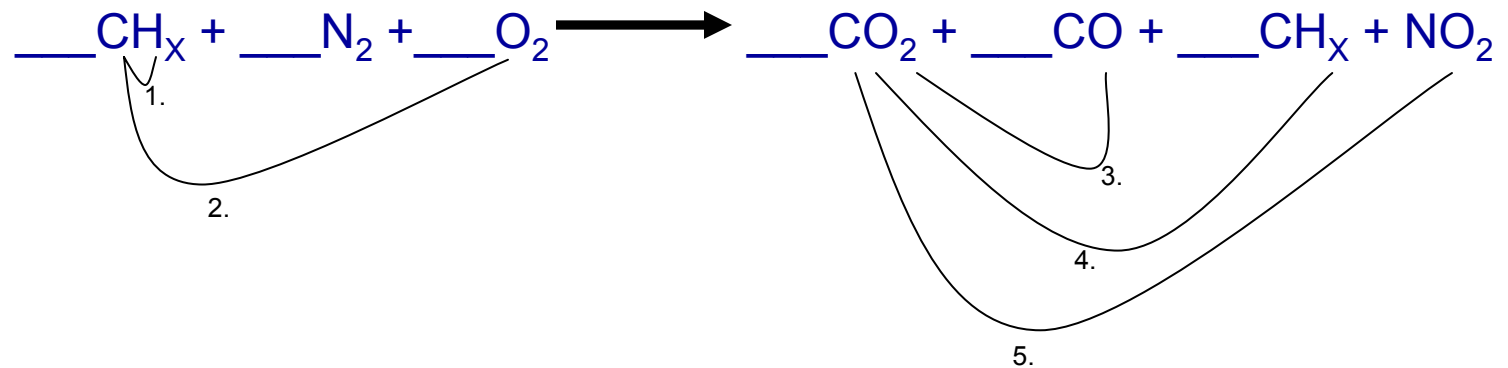
Size of equipment enlarged for presentation purposes



# RSD Mathematics

## 2. Software –

- a. Measure ratios in order to calculate concentrations



- b. “Ratios to Concentrations”

- a. Simple Explanation - [http://www.rsd-remotesensing.com/user\\_info.asp](http://www.rsd-remotesensing.com/user_info.asp) under RSD for non-technicals.
- b. Derivation Math - <http://www.feat.biochem.du.edu/whatsafeat.html> under standard combustion equation.



# History & Evolution

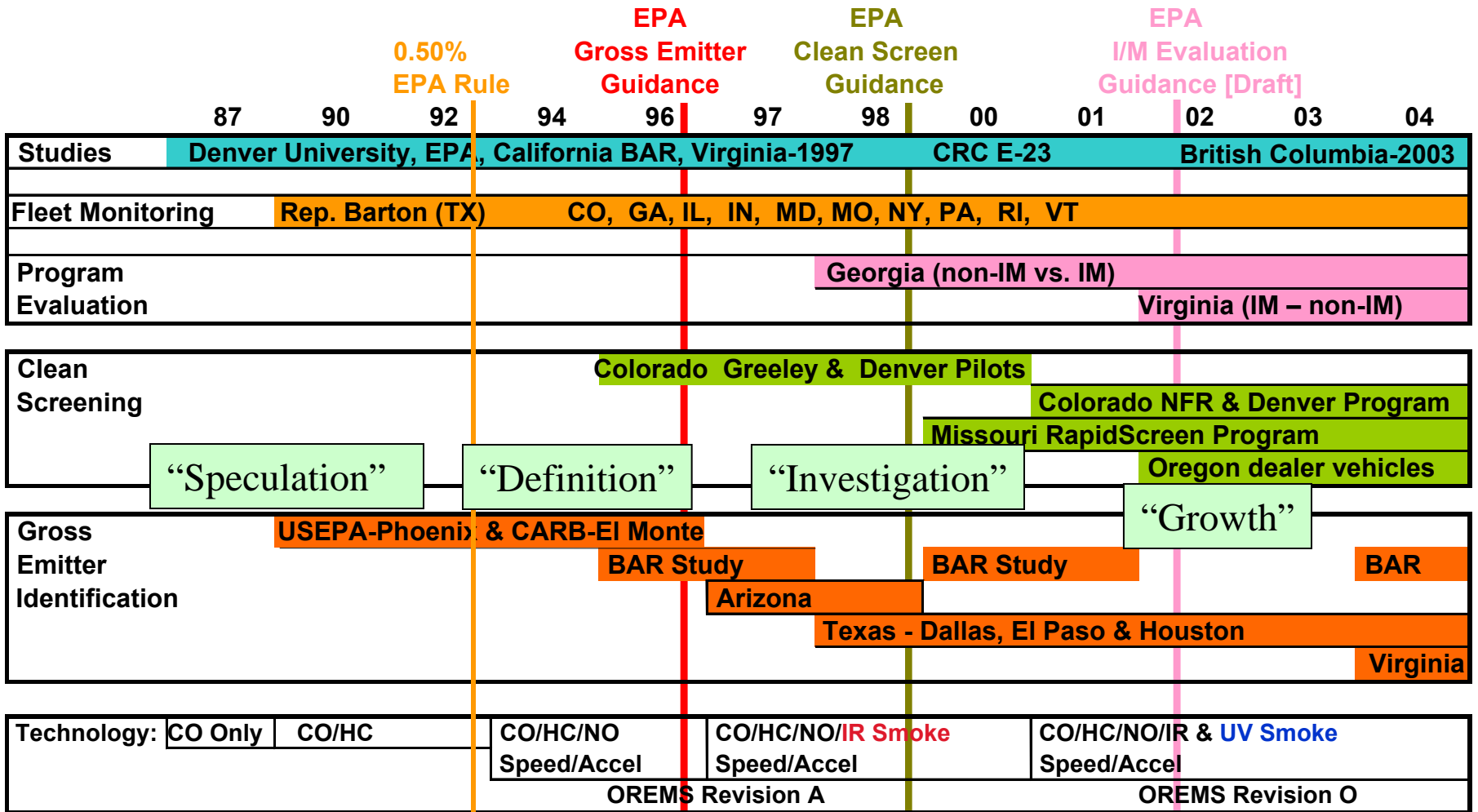


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# History of Remote Sensing (in the USA)



# Applications & Regulations

“Guidance Documents”



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# USEPA Guidance Documents



1. **Gross Emitter Identification – EPA/AA/AMD/EIG/96-01**
  - a. United States: Texas (since '99), Virginia (July 2004)
  - b. International: Taiwan (since 2002)



2. **Clean Screening – EPA420-P-98-07**
  - a. United States: Missouri (since '00), Colorado (since 01)



3. **Program Evaluation – EPA420-B-02-001**
  1. United States: Georgia (GIT-"developed Reference Method")  
Colorado (UofD-"developed Step Method")  
Virginia (ESP-applied Reference)  
British Columbia (ESP-applied Reference)
  2. International (Fleet Characterization) : Sri Lanka (03), Singapore (since 03),  
India (since 03).

# Technology & Performance



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# Performance Summary

What it took to get where we are...for LDGVs.

- Technology (HW & SW) – Done [NH<sub>3</sub>, Cold, Unmanned]
- Matching Laboratory Analyzers - Done
- Matching Inspection Results - Done
- Matching Fleet Emissions – Done

What it will take to get where we want to go...for DVs.

1. Technology (HW & SW) – SF Done [NO<sub>2</sub>, SO<sub>2</sub> Begun]
2. Matching Laboratory Analyzers - NO done [SF Begun]
3. Matching Inspection Results – NO done [SF Begun]
4. Matching Fleet Emissions - ?

# Light Duty Gasoline Measurements

“Demonstrated Performance”



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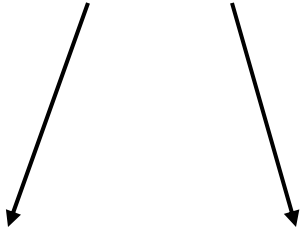




# LD Gasoline Measurement Technology

- Today:
- CO, HC, CO<sub>2</sub> - NDIR
  - NO - DUV
  - S/A System
  - Camera (No ALPR)

- In Development:
- NH<sub>3</sub> – DUV
  - Cold Start Detection
  - Unattended

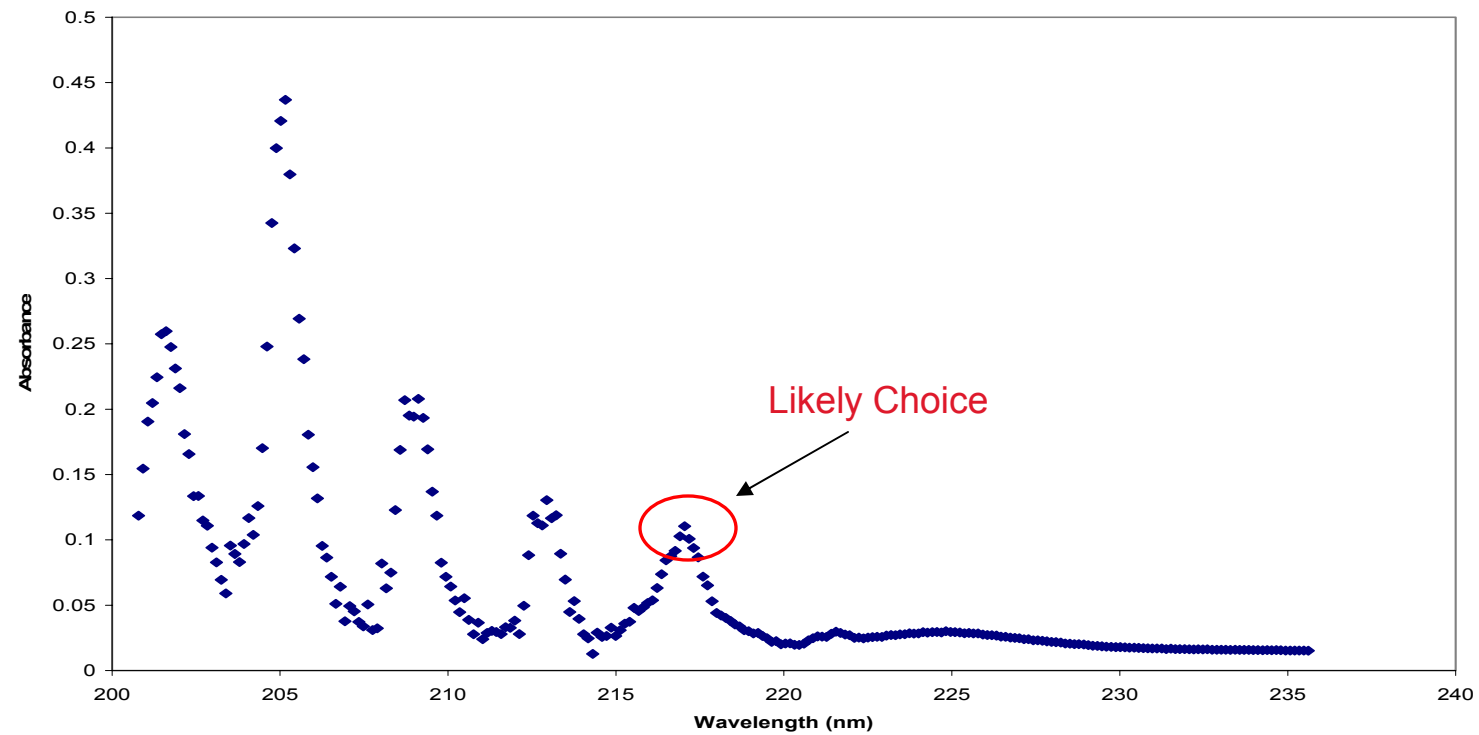


Gas amounts  
↑  
time  
Gas ratios





# NH<sub>3</sub> Measurement



- Peaks within UV Spectrometer range
- Detection limits being explored.
- Previously done by Baum using similar technology.

# INFRARED THERMAL IMAGING OF AUTOMOBILES:

## Identification of Cold Start Vehicles

Angela M. Monateri, Donald H. Stedman, Gary A. Bishop

University of Denver, Department of Chemistry and Biochemistry

2190 E. Iliff Ave., Denver, CO, 80208

### Introduction

On-road studies identify cold start vehicles as high emitters, even though they have no repairable fault. This study investigates the use of thermal infrared imaging to identify vehicles that are high emitting because they are "cold."

Cold vehicles can be differentiated from hot vehicles by infrared imaging, which can distinguish between:

- Hot and cold exhaust system metal parts
- Hot and cold reflections of the underbody of the vehicle from the road surface
- Tires that have a uniform and bright IR emission identify hot vehicles, contrasting with cold tires, or tires that are non-uniformly hot, mostly due to solar warming.

A FLIR A20V Infrared Camera was used to look at the infrared image from an automobile.

The camera was set up with a FEAT 3000 unit to compare emissions vs. the reflected heat to detect if the vehicle was hot or cold.

- Study at a Denver high school in which the vehicles are known to be cold
- Parking lot study on vehicle warm up emissions and IR image

### Cold Start Emissions

Vehicles emit higher amounts of CO and hydrocarbons (HC) right after the vehicle has been started because the vehicle is running rich. Extra fuel is added to the combustion chamber in order to ensure ignition. Therefore a vehicle that is cold, with high emissions, has no repairable fault, while a hot vehicle with high emissions does have repairable fault.

Fuel enrichment causes incomplete combustion and results in increased unburned HC and CO in the exhaust before catalyst light-off.

As the vehicle's oxygen sensor and catalyst heat up, CO and HC concentrations decrease.

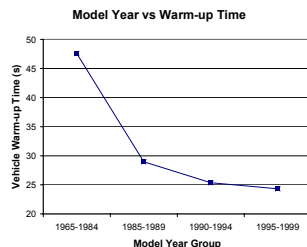
### Analysis of CE-CERT FTP Data

FTP vehicle data with MY 1965-1999 were obtained from Barth, *et al.* 2000.

This FTP vehicle data were plotted as a function of time versus (CO/CO<sub>2</sub>). The resulting graph was then used to determine 90% emissions recovery, i.e. the time it took for the vehicle emissions to return from the maximum to within 90%, for each vehicle in the data set. The time was then plotted against the age of the vehicle.

Based on this data treatment, the average catalyst light-off time was less than 30 seconds.

Vehicles produced after 1999 would be expected to display even shorter light-off times based on newer technology.



The above graph is of the FTP data put into five year MY bins, with the exception of 1965-1984, comparing catalyst light-off times vs. MY. These data are in agreement with Younglove, *et al.* 1999, who state that "...light-off times were found to be decreasing with newer model years."

### FLIR Thermovision A20V Infrared Camera

- Field of View: 25°
- Spectral Range: 7.5-13 μm
- Detector: Focal Point Array, Uncooled microbolometer
- Thermal Sensitivity: 90-120 mK at 25° C

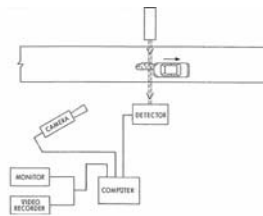


References:  
 Younglove, T.; Levine, C.; Barth, M. J.; Scora, G.; Norbeck, J. M. In *Analysis of Catalyst Efficiency Differences Observed in an In-Use Light Duty Vehicle Test Fleet*. Proceedings of the CRC, San Diego, CA, April 19-21, 1999.  
 Barth, M.; AN, F.; Younglove, T.; Scora, G.; Levine, C.; Ross, M.; Wenzel, T. *Development of a Comprehensive Modal Emissions Model*. Final Report NCHRP Project 25-11, April, 2000.

### Camera Setup

First the camera is set to a black and white color scale, with white being the hottest color; this is done because it is an intuitive color scheme and is easy for everyone to interpret. The camera is focused, set to the manual mode and is calibrated by holding down the SEL button on the top of the camera. This is done while aiming the camera at a known hot vehicle with the road surface in the FOV. For this setting we ensure that the hot exhaust system or underbody of the vehicle cannot be seen. The temperature scale is adjusted by changing the level and span scale on the camera in order to see small changes in reflected energy off the road surface. The level and scan can be likened to brightness and contrast respectively, which sets the scale of reflected energy between which the camera recognizes. While the above guidelines are specific to the FLIR A20V, other types of camera's should be set up similarly.

### On-Road Setup with FEAT 3000 Unit



### Regis High School

An underclassmen parking lot, in which most of the vehicles had been sitting since the morning had been chosen.

FEAT 3000 unit was set up across parking lot access road to measure the emissions of vehicles entering and leaving the lot. Most of the vehicle entering the lot should be hot, while those leaving the lot should be cold.

332 vehicles were measured on two consecutive days.

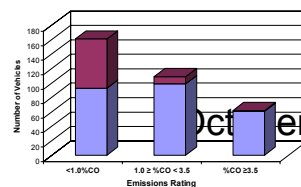
### Analysis of Data

Emissions data from the FEAT 3000 unit is extracted from computer, and the invalid vehicles removed.

The video tape of recorded IR images are watched, and it is decided if the vehicle is hot or cold based on heat signatures that are emitted and reflected from the vehicle.

- Bright reflections off road surface
- Very hot tailpipes
- Uniform heat emitted from tire treads.

The vehicle is noted as either hot or cold in a spreadsheet.



October 2002

	<1.0%CO	1.0-2.0%CO	>2.0%CO
Count	93	99	61
Hot	68	10	1
Percent	48.5	32.8	18.7

This graph shows the number of vehicles that received a GOOD, FAIR, or POOR rating, as well as if the vehicle was a cold or hot vehicle. Only one vehicle received both a POOR rating and was a hot vehicle from both days of measuring vehicles at the high school.



One vehicle from cold start to beyond catalyst light-off time. CO emissions are from 2.87% at cold start to 0.19% after warming up. Emissions of CO decrease with rising exhaust temperatures. In little over 5 minutes, this 1986 Chevy Celebrity (Blue) has warmed up enough to control its emissions.

### Snow on Road Surfaces

Snow is a mostly absorbing surface in the infrared, however liquid water is very reflective in the infrared.

Breckenridge Ski Area patrol SUV had very little reflection on the snow covered parking lot surface.

Tire treads are also cooled in the snow, and therefore are not emitting higher IR and appear to be cold, even if the vehicle had been driving around.



Both of the vehicles in the IR images above are hot, however because snow does not reflect IR radiation, there is no reflection on the road from the underbody of the vehicles.

### Conclusions

- An infrared camera can be used to differentiate between hot and cold cars on the road based on the thermal reflection that radiates from the underbody of automobiles.
- Cold cars will have the same IR reflection as the road, or only a slightly "brighter" reflection than the road. Hot vehicles will have a very intense, bright reflection off the road surface.
- When combined with a FEAT unit, vehicles can be correctly identified as gross emitters of pollution. Cold vehicles will be higher emitters, and given to incorporating an infrared camera with a FEAT unit, these vehicles would be previous a POOR rating.
- Snow is not a good surface for observing infrared images of vehicles because it is not very reflective, and also cools tires so that the heat being emitted from the tires cannot be seen in the IR.

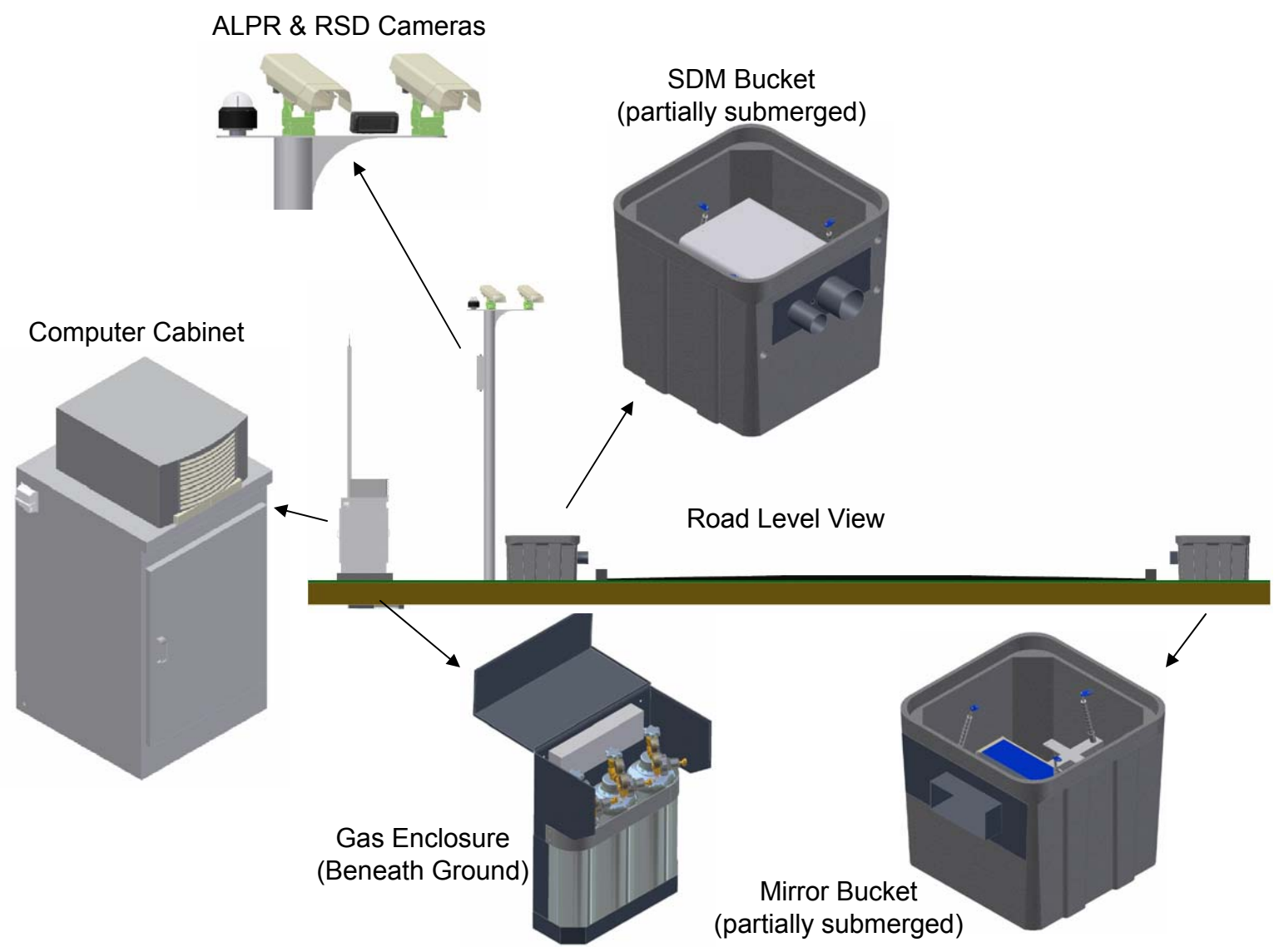
### Future Work

- Using the IR camera determine hot and cold vehicle signatures on hot road surfaces. (Las Vegas, May 2004)
- Software still need to be written in order to incorporate the infrared camera with the visual camera and the FEAT.





# Unmanned Concept "2002"





# Unmanned Alpha Test Site - Tucson

"2004"



# Matching Laboratory Analyzers

## Gasoline Vehicles



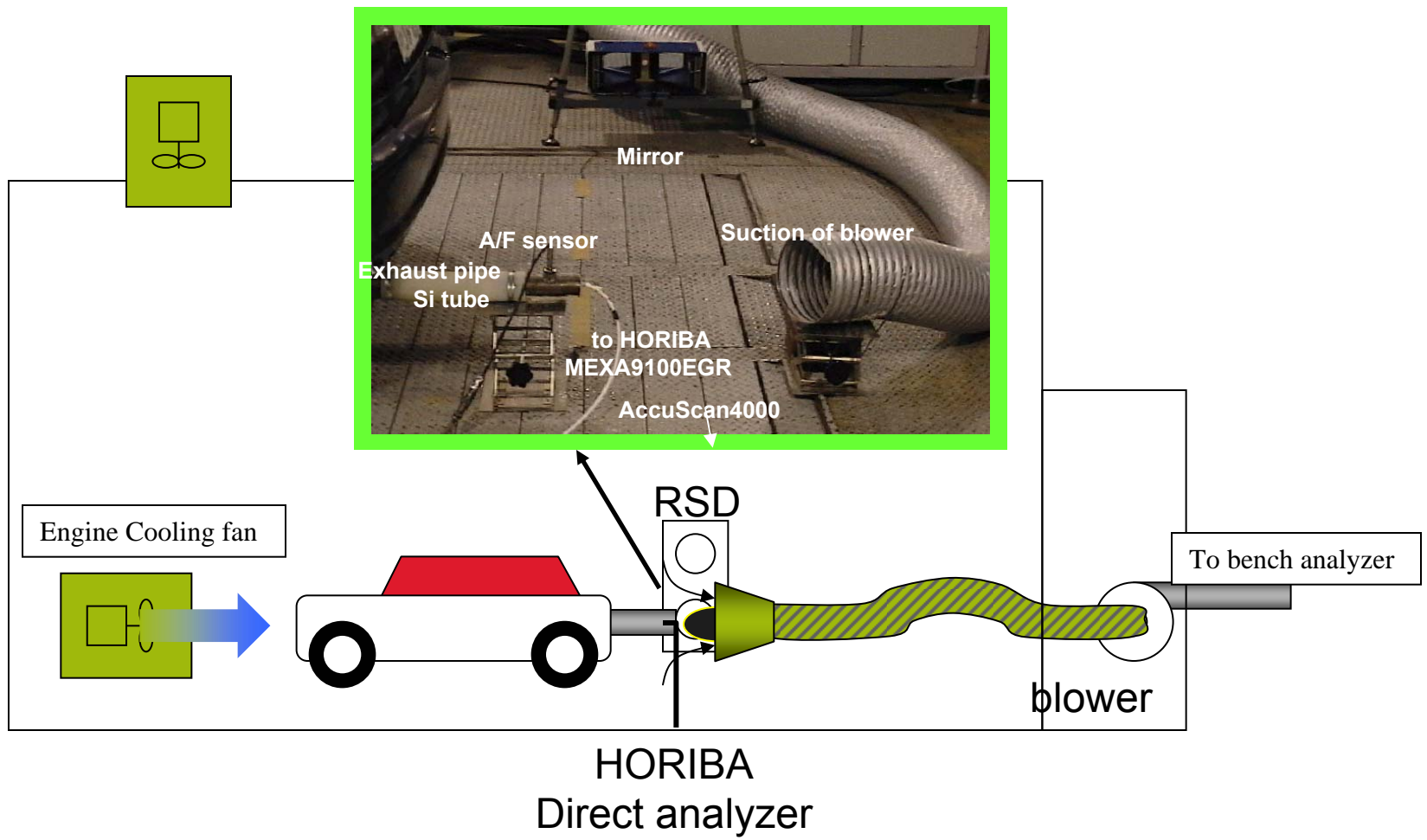
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# Correlation Test Setup

Japan Petroleum Energy Center – February 2003





# Correlation Test Method

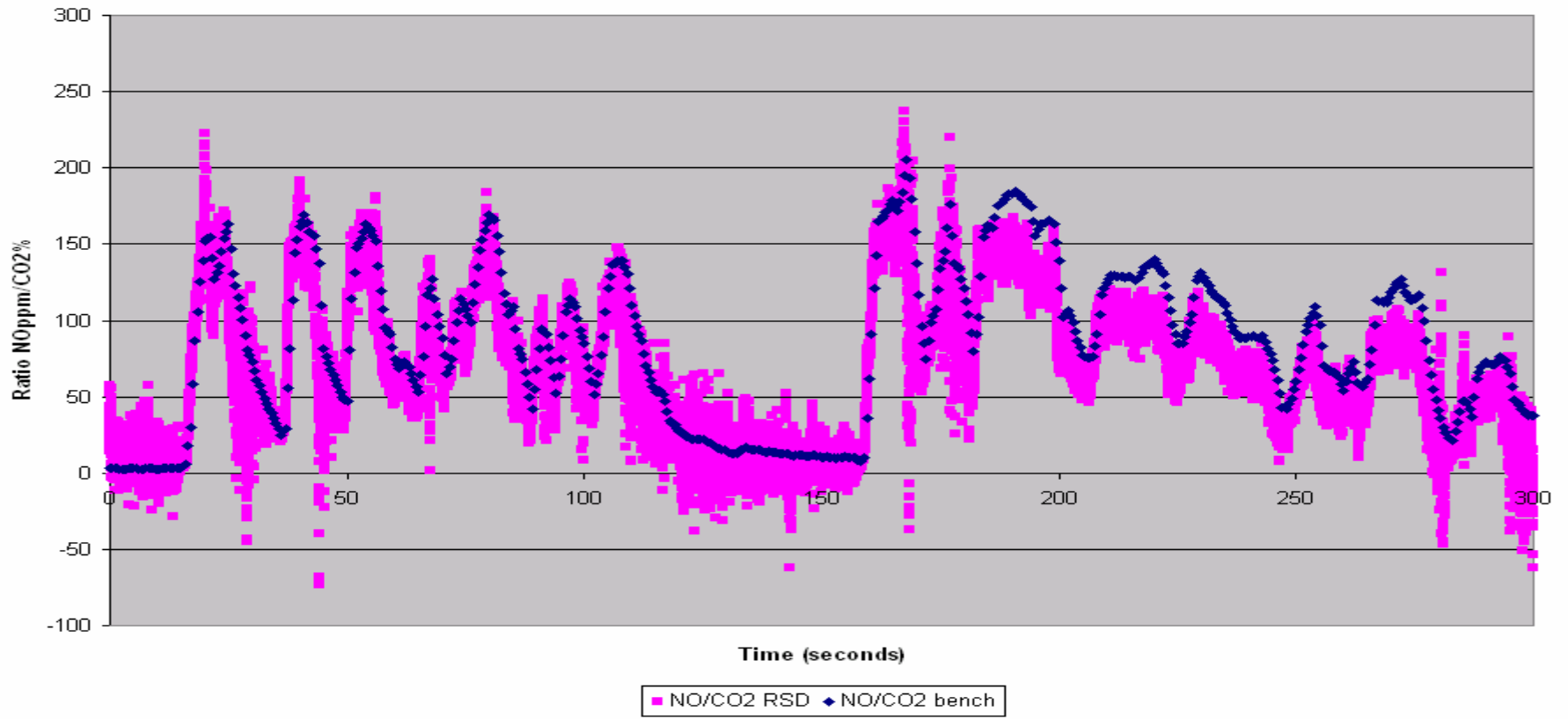
- Several different drive modes were utilized to test the effectiveness of the RSD.
  - LA4 drive mode
  - Steady state drive modes (60,40,20kph)
  
- Horiba bench analyzers were compared to RSD.
  - Comparisons between the Horiba bench analyzers and the RSD unit were the gas ratios and their mean values.
    - CO/CO<sub>2</sub>, HC/CO<sub>2</sub>, NO/CO<sub>2</sub>



# Correlation Test Results

## Mitsubishi Lancer

Mitsubishi Lancer LA4 drive mdoe



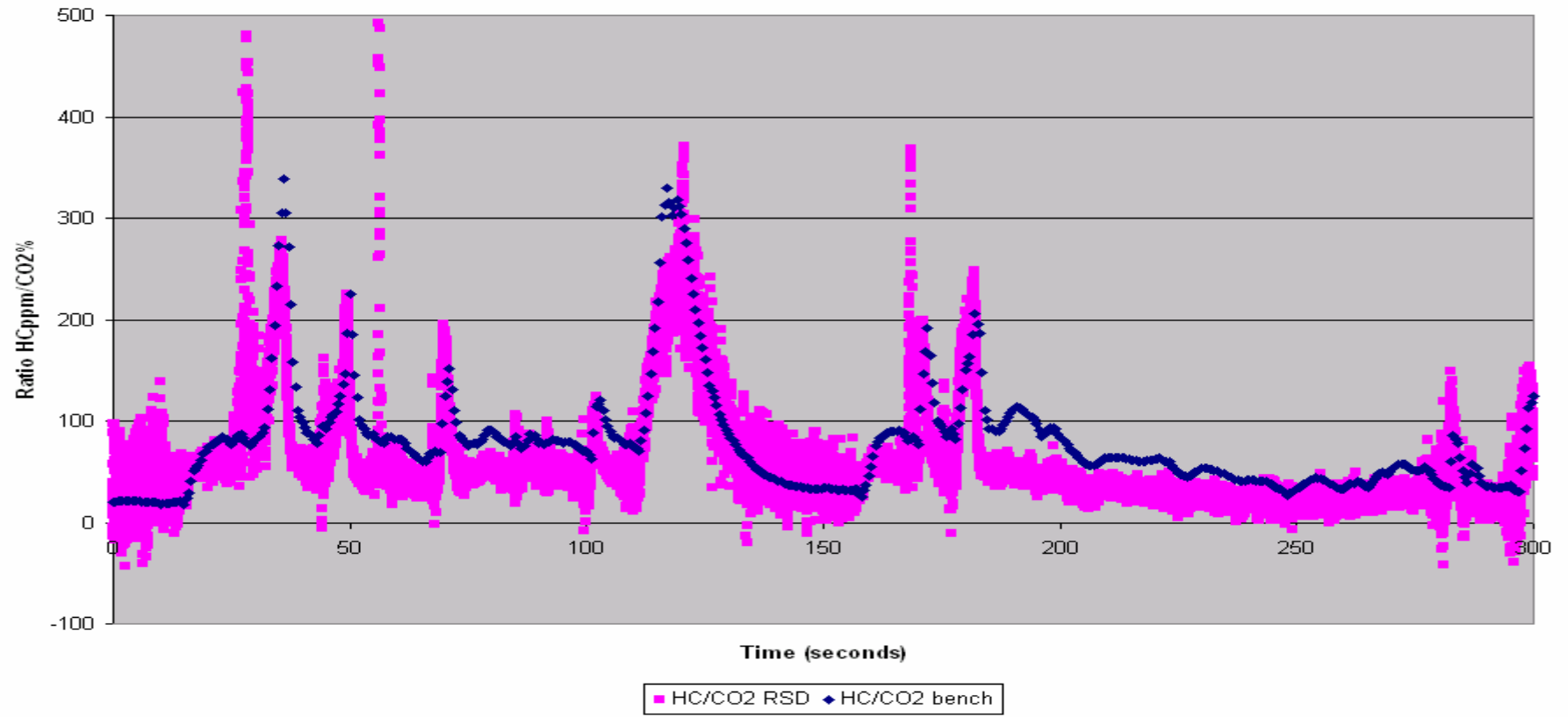




# Correlation Test Results

## Mitsubishi Lancer

Mistubishi Lancer LA4 drive mode

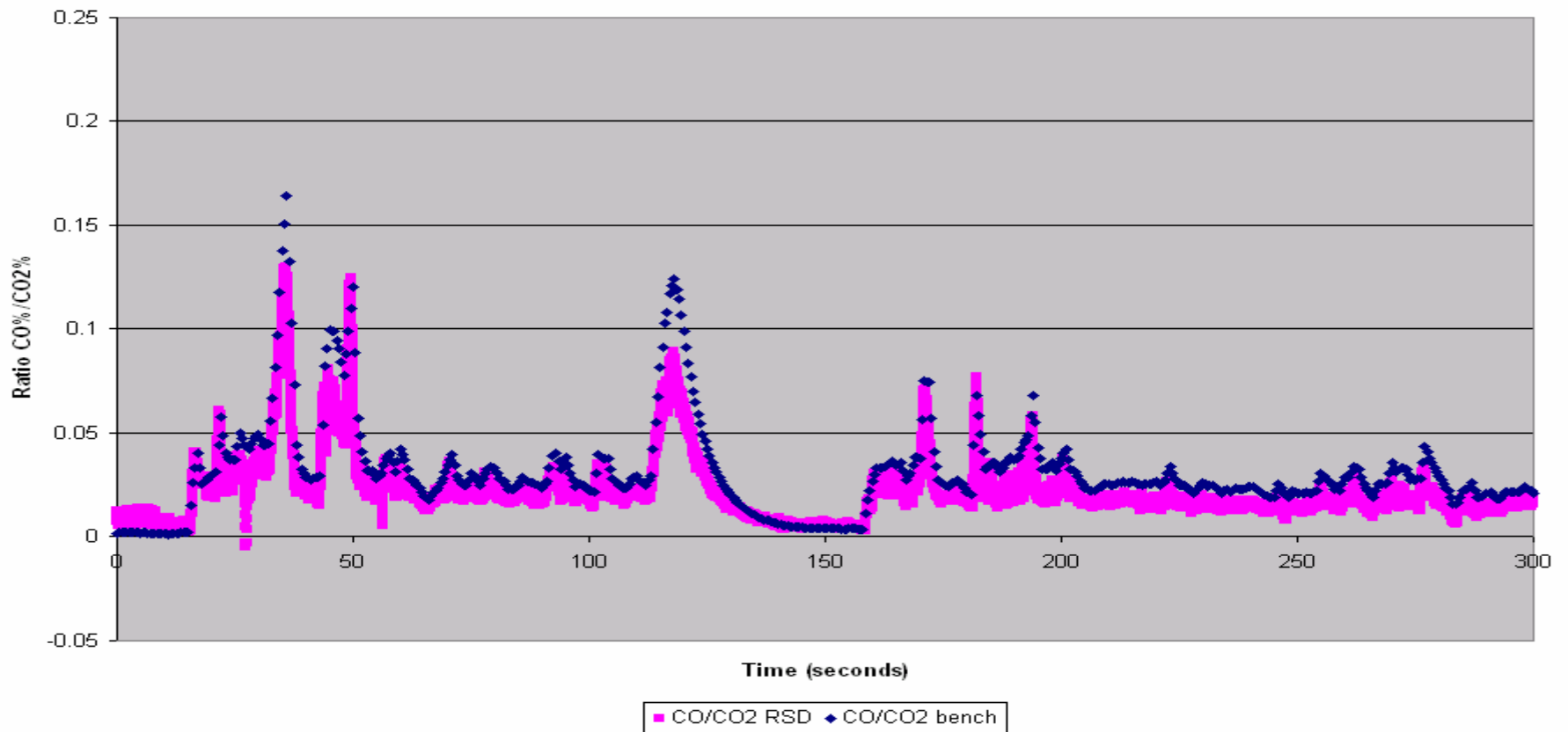




# Correlation Test Results

## Mitsubishi Lancer

Mitsubishi Lancer LA4 drive mode





# Correlation Result

## Mean ratio comparison

Mean difference = RSD mean ratio – Bench mean ratio

- Mitsubishi Lancer
  - Mean diff CO%/CO2%
    - -0.022% CO per percent CO2
  - Mean diff HCppm/CO2%
    - -10.3 ppm HC per percent CO2
  - Mean diff NOppm/CO2%
    - -29.2 ppm NO per percent CO2



# Conclusion

## JCAP

- Good correlation between the Horiba bench gas analyzers and the ESP AccuScan4000 (near stoichiometric operation).
  - Accurate tracking of transient events.
  - Good mean gas ratio comparison.

[Back to Performance Summary](#)

# Matching Inspection Results

## Gasoline Vehicles



August 04





# Clean Screening

## Missouri



1. Started in St. Louis in April 2000
2. Designed with IM240
3. ~ 5M measurements annually
  - 5 RSD-3000s (2 shifts – total 14 hours/day)
4. 2 clean in-cycle measurements → CS
  - Cutpoints: 0.5%CO, 200ppmHC, 1500ppmNOx
5. ~ 150k exemption notices annually
6. 20 to 25% of initial inspections
7. Performance measured by 2% random audit
  - Amount of Excess Emissions False Passes represent.



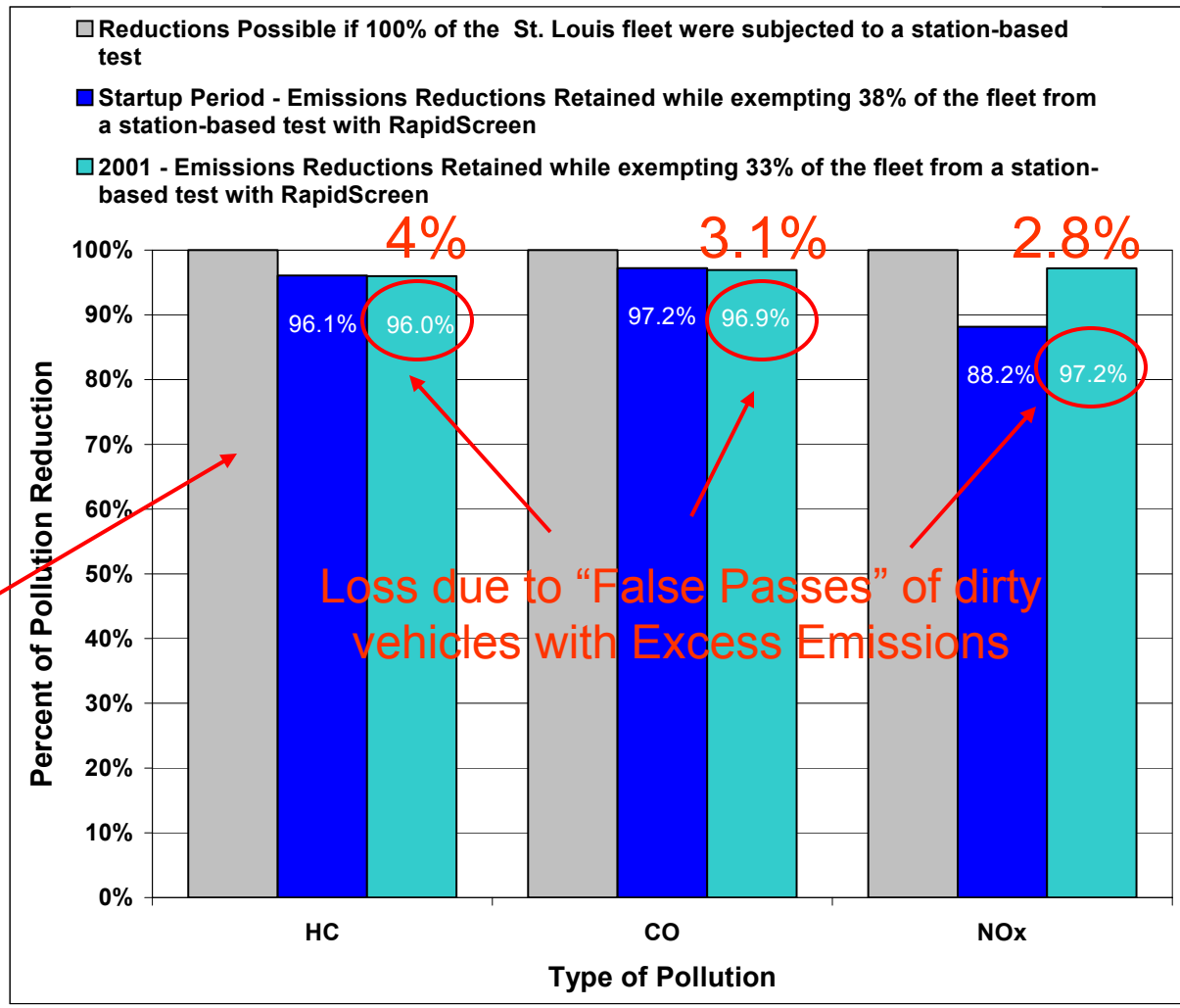
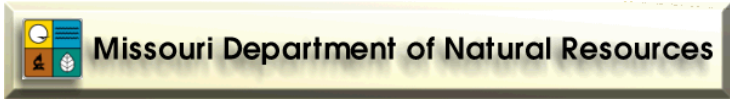
# Definition of Excess Tailpipe Emissions





# Identifying Clean Vehicles – Results

## “Loss of Excess Emissions”



Perfect Inspection - 100% of Excess Emissions Identified

Loss due to “False Passes” of dirty vehicles with Excess Emissions

4%

3.1%

2.8%





# Gross Emitter Identification

## Gasoline Vehicles





# BAR Pullover Study

## LD Gasoline Vehicles

**Final Report 2001 - 06**  
**August 30, 2001**

### REMOTE SENSING DEVICE HIGH EMITTER IDENTIFICATION WITH CONFIRMATORY ROADSIDE INSPECTION



*Bureau of Automotive Repair*  
*Engineering and Research Branch*



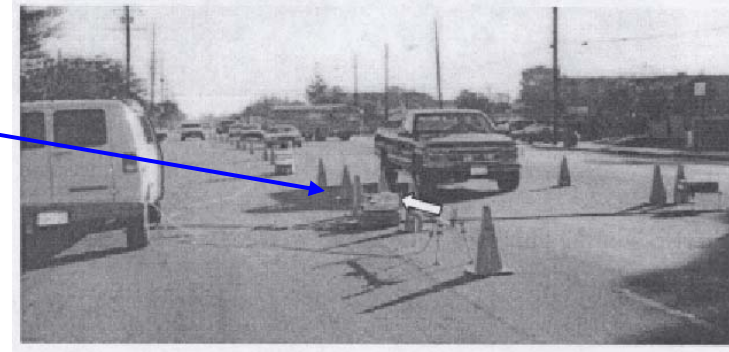


# BAR Pullover Study

## LD Gasoline Vehicles

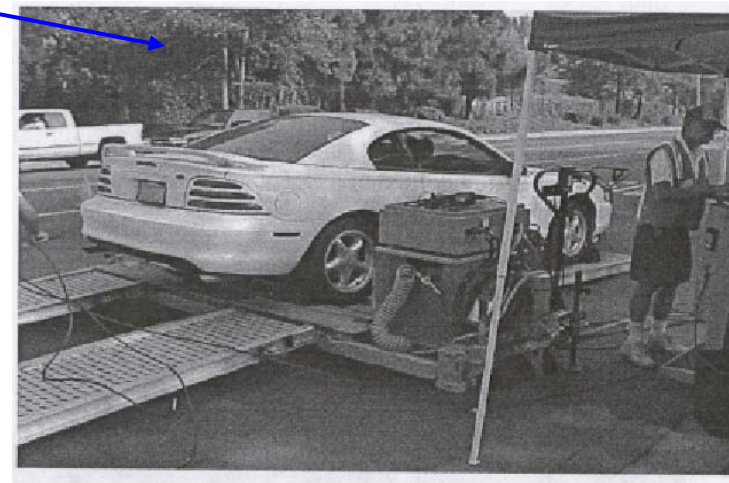
### Upstream Dual RSD Screen:

Dual Stedman FEATs 3005 & 3006



Vehicles exceeding 1% CO, 500ppm HC, 500ppm NO  
on either RSD

### Downstream Roadside ASM:





# BAR Pullover Study Results

Sample: 326 had at least 1 RSD & and an ASM test

**Pull-over Distribution by Pollutant Combination and FEAT Unit**

Cutpoint Exceeded	3005		3006	
	Number	Percent	Number	Percent
HC only	6	2.2	6	4.5
CO only	55	19.9	20	14.9
NO only	65	23.6	18	13.4
HC and CO	95	34.4	66	49.3
HC and NO	17	6.2	11	8.2
CO and NO	15	5.4	6	4.5
HC and CO and NO	23	8.3	7	5.2
<b>Total:</b>	276	100.0	134	100.0

Implication: Perhaps HC channel can be excluded.

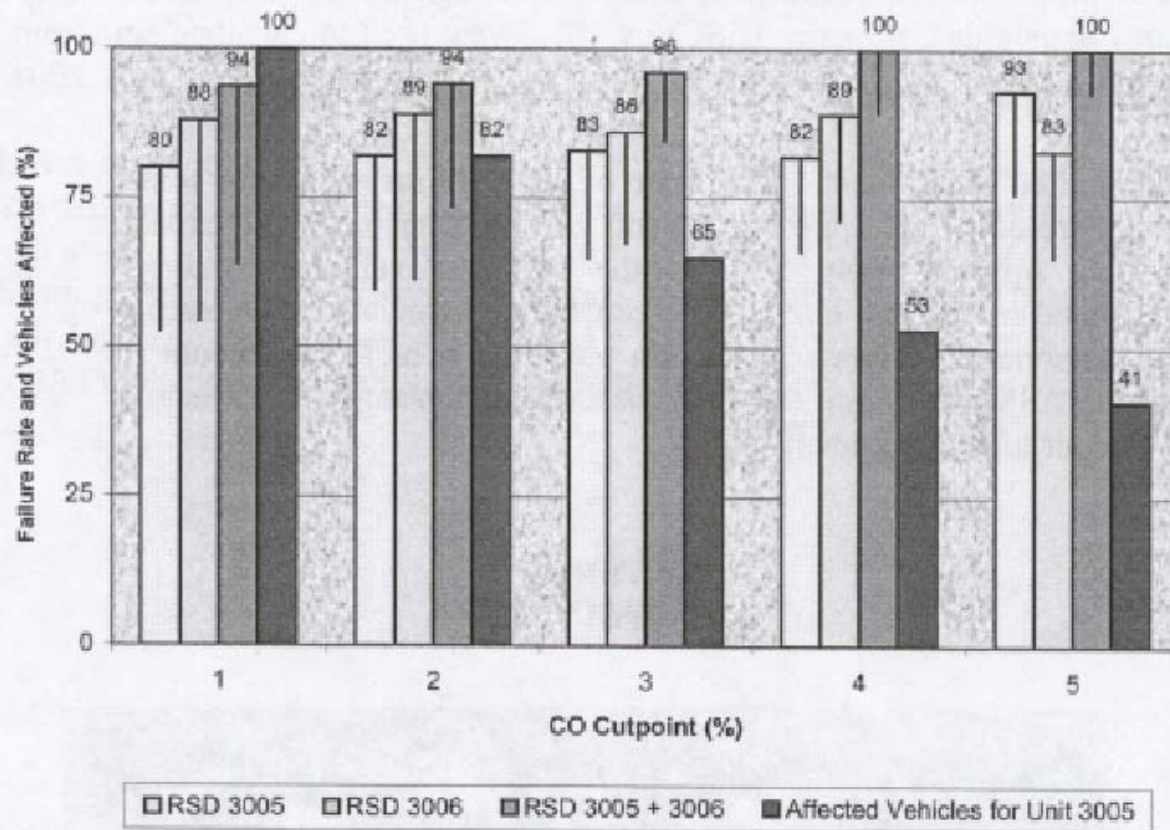
Implication: Maybe together they are better than either alone.



# BAR Pullover Study

## CO Results

**FIGURE 4**  
**ASM Inspection Failure Rate for RSD Identified CO HEVs**

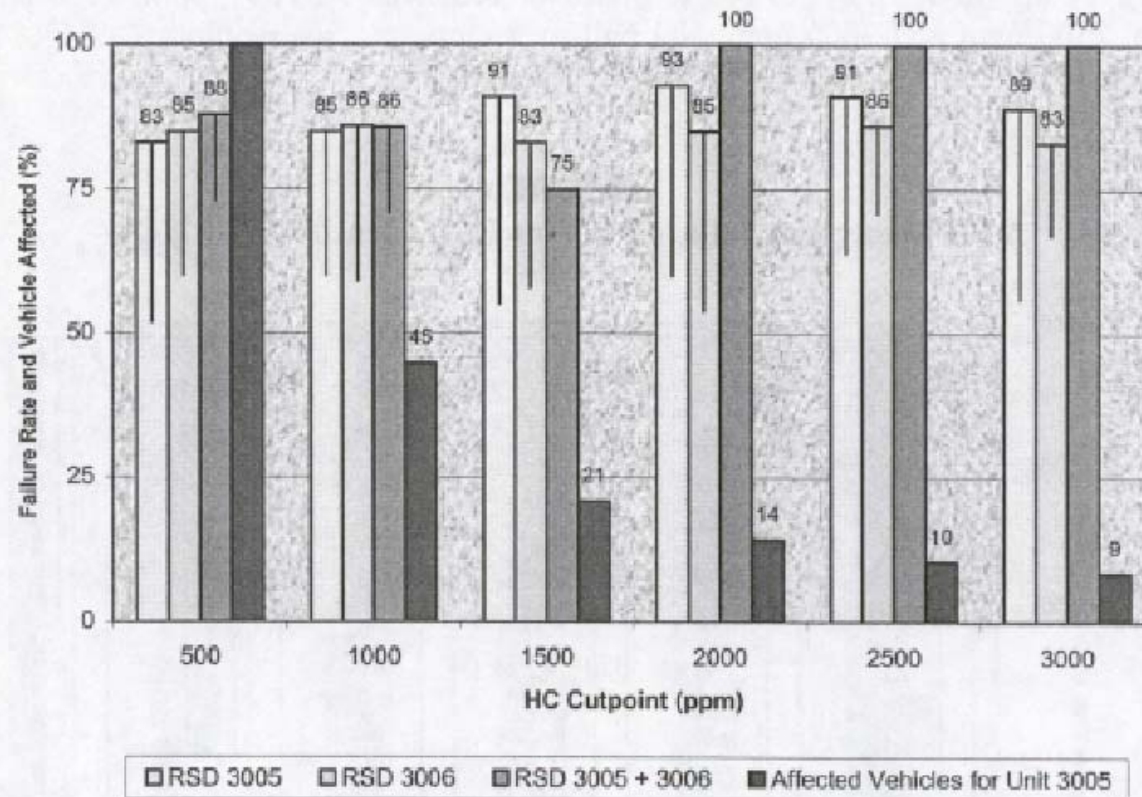


*Note: Lines within bars indicate the portion of the ASM inspection failure rate due to other than CO failure.*



# BAR Pullover Study HC Results

**FIGURE 5**  
**ASM Inspection Failure Rate for RSD Identified HC HEVs**

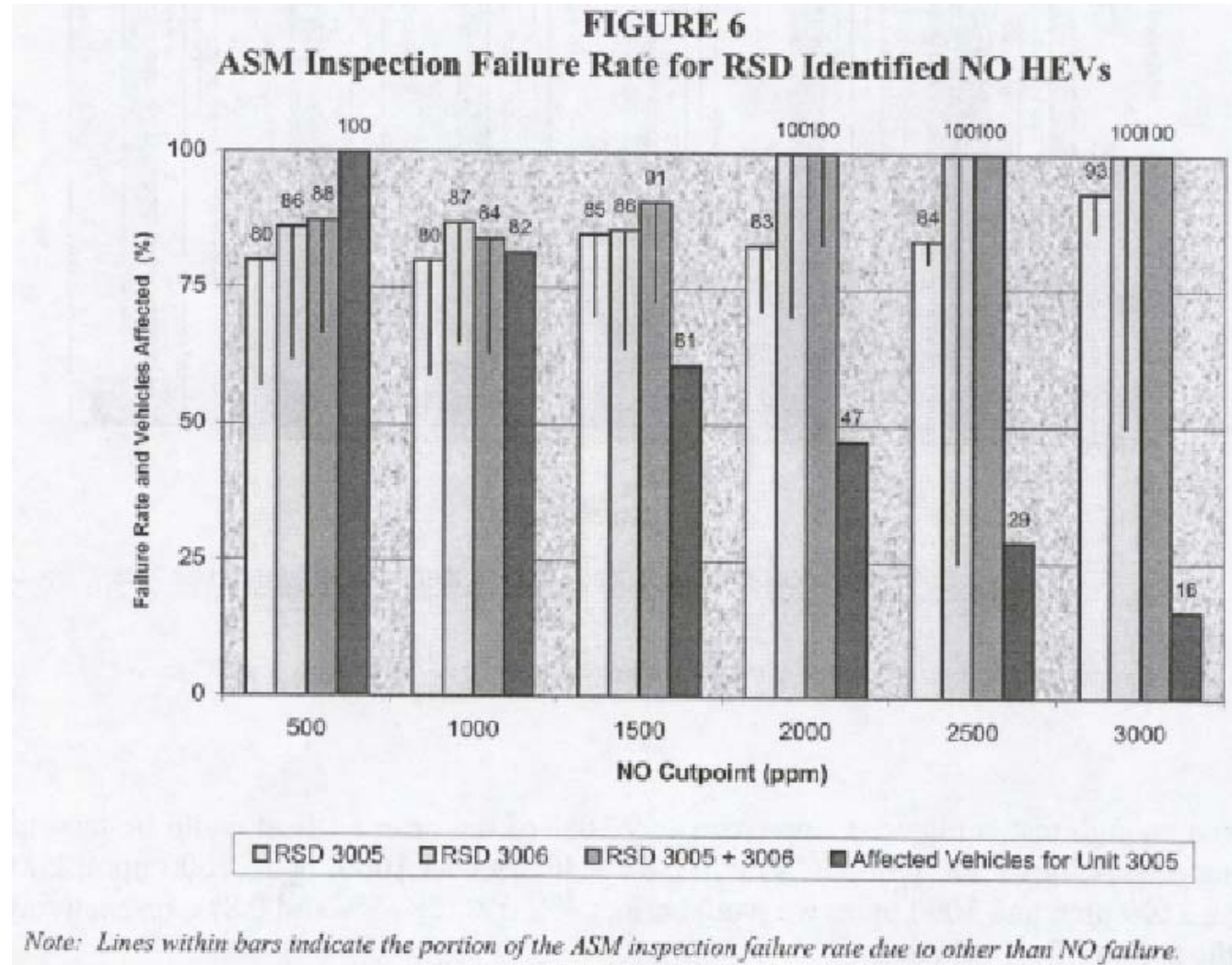


*Note: Lines within bars indicate the portion of the ASM inspection failure rate due to other than HC failure.*



# BAR Pullover Study

## NO Results





# BAR Pullover Study

## Conclusions

### CONCLUSIONS

In conclusion, RSD has proven to be an effective tool for high emitting vehicle identification. By targeting vehicles with RSD emission readings exceeding 2% CO or 1,000 ppm HC or 1,500 ppm NO, we can expect at least an 83% to 88% ASM inspection failure rate. By adding multiple RSD readings exceeding the predetermined cutpoint, we can increase the successful identification of high emitting vehicles to at least 92%. The

- Cutpoints: 2% CO, 1000ppm HC, 1500ppm NO
- 83% - 88% ASM Failure (1 RSD Observations)
- 92% ASM Failure (2 RSD Observations)





# Identifying High Emitters – Results

## “False Failure Rate”

1. California RSD pull-over study results reported:
  - a. 1989 Lynwood:
    - i. 86% of vehicles with RSD >2% CO failed roadside inspection
  - b. SCAQMD 1996:
    - i. 95% of vehicles with RSD >4% CO or 1,000 ppm HC failed IM240
  - c. BAR 2001:
    - i. 83-88% of vehicles with RSD >2% CO or 1000ppm HC or 1,500 ppm NOx failed ASM

[Back to Performance Summary](#)

# Matching Fleet Emissions

## LD Gasoline Vehicles



August 04





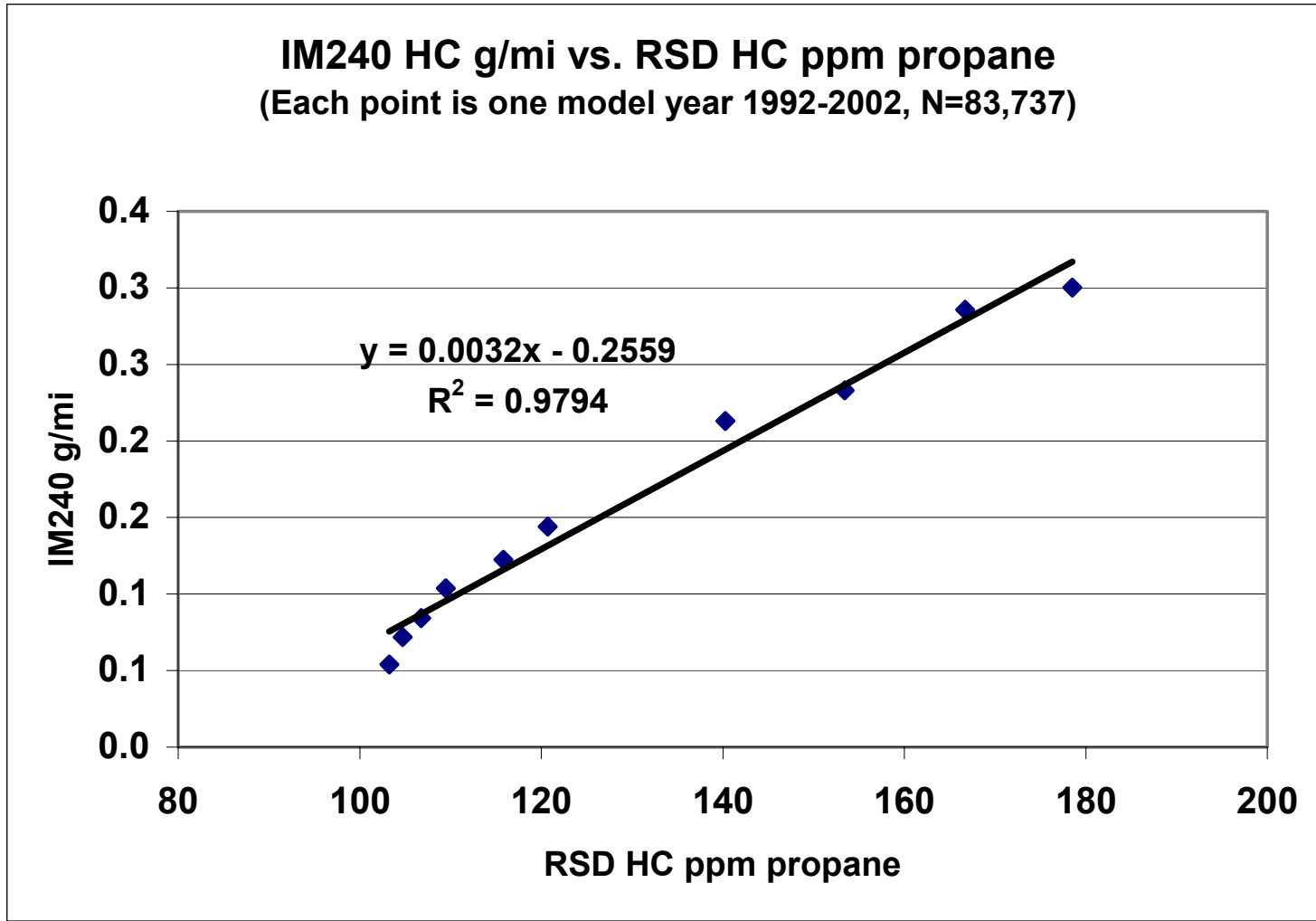
# Correlation With IM240 Tests

## Vancouver Fleet Characterization

- 150,000 valids RSD readings
- RSD mostly after IM240 tests
- Average emissions by model year
- 1992 – 2001 models
- Model year average correlation,  $R^2$ :
  - CO 0.96
  - HC 0.98
  - NOx 0.99
- RSD HC readings biased high (software)

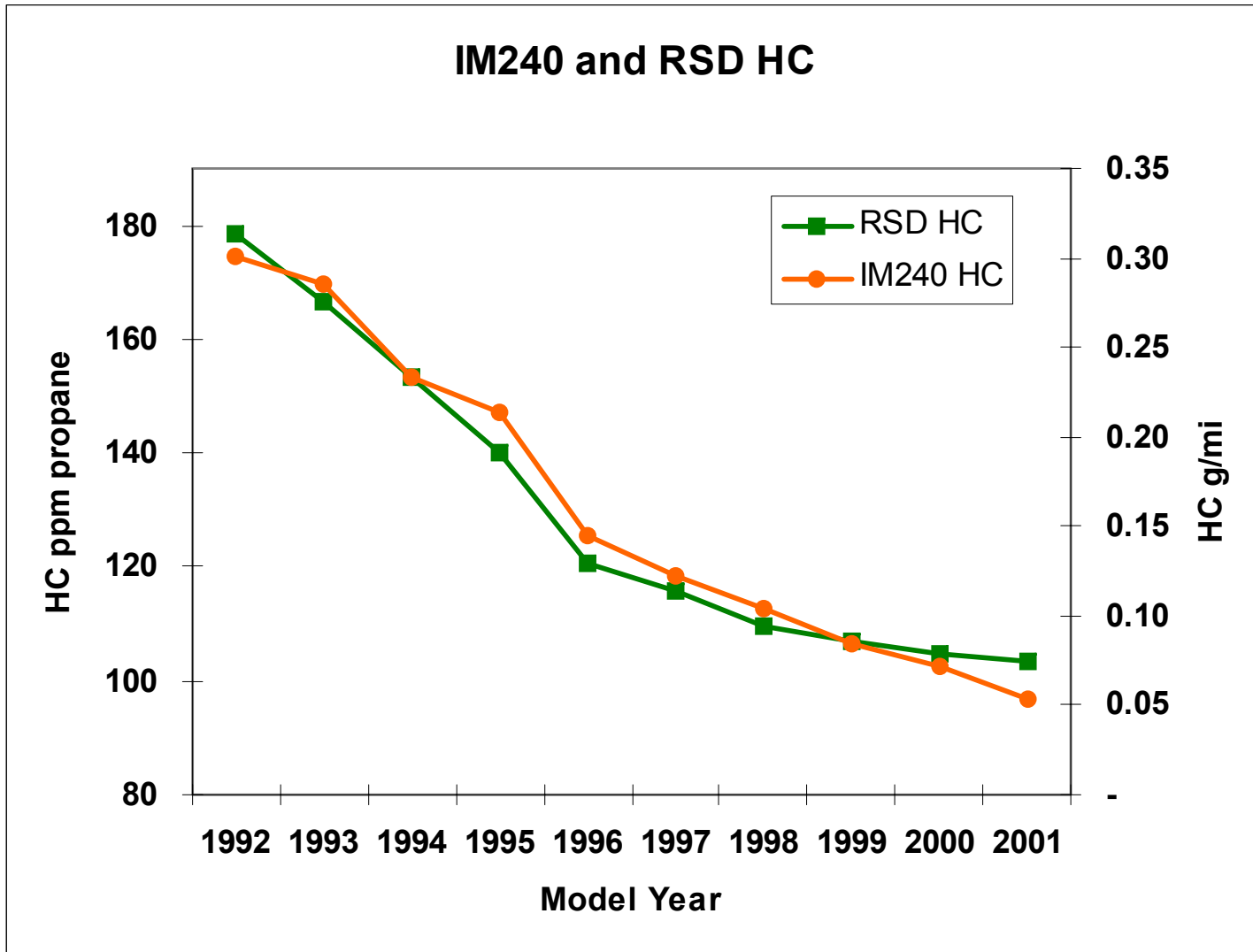


# RSD vs. I/M 240 - HC



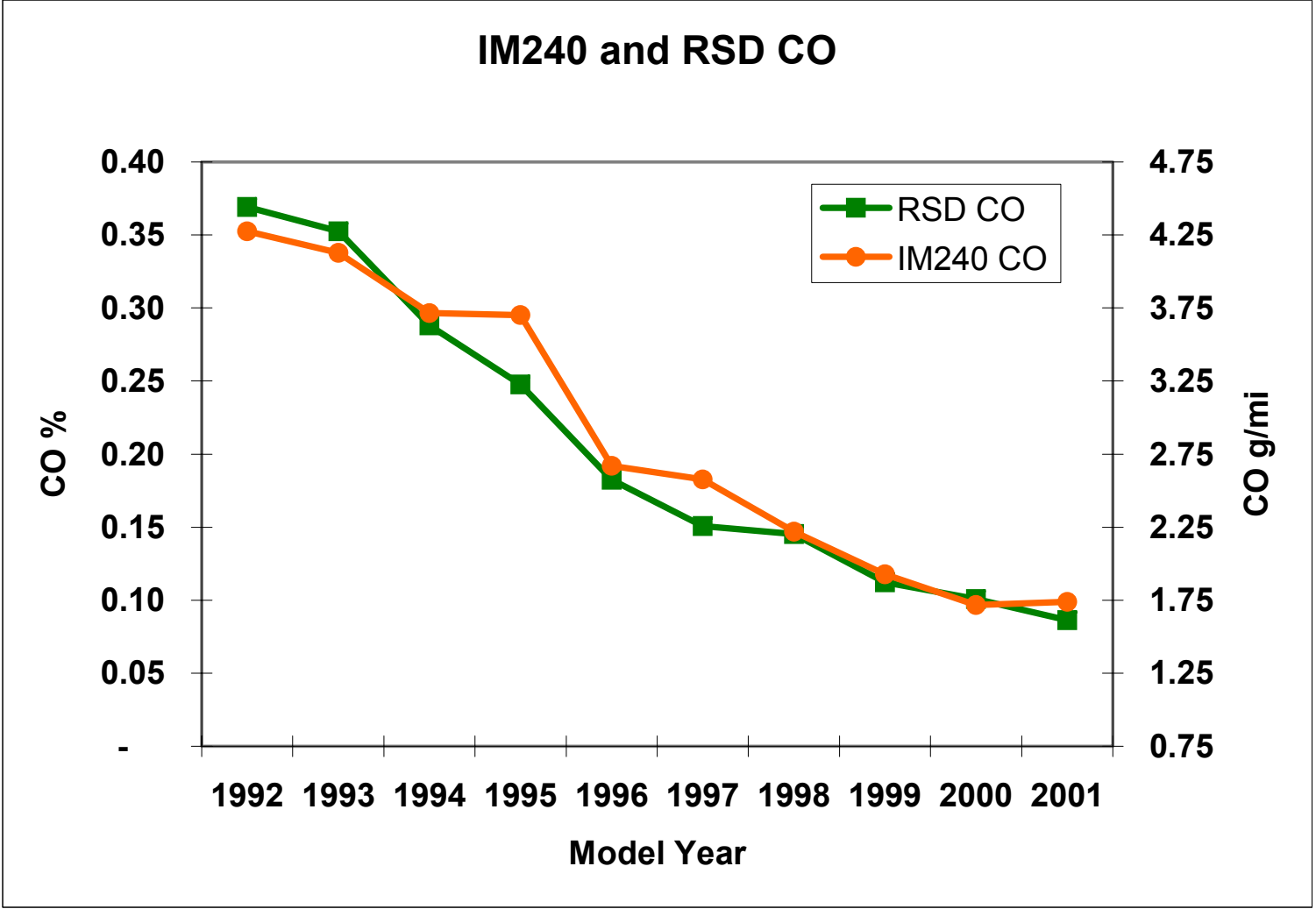


# RSD and I/M 240 - HC



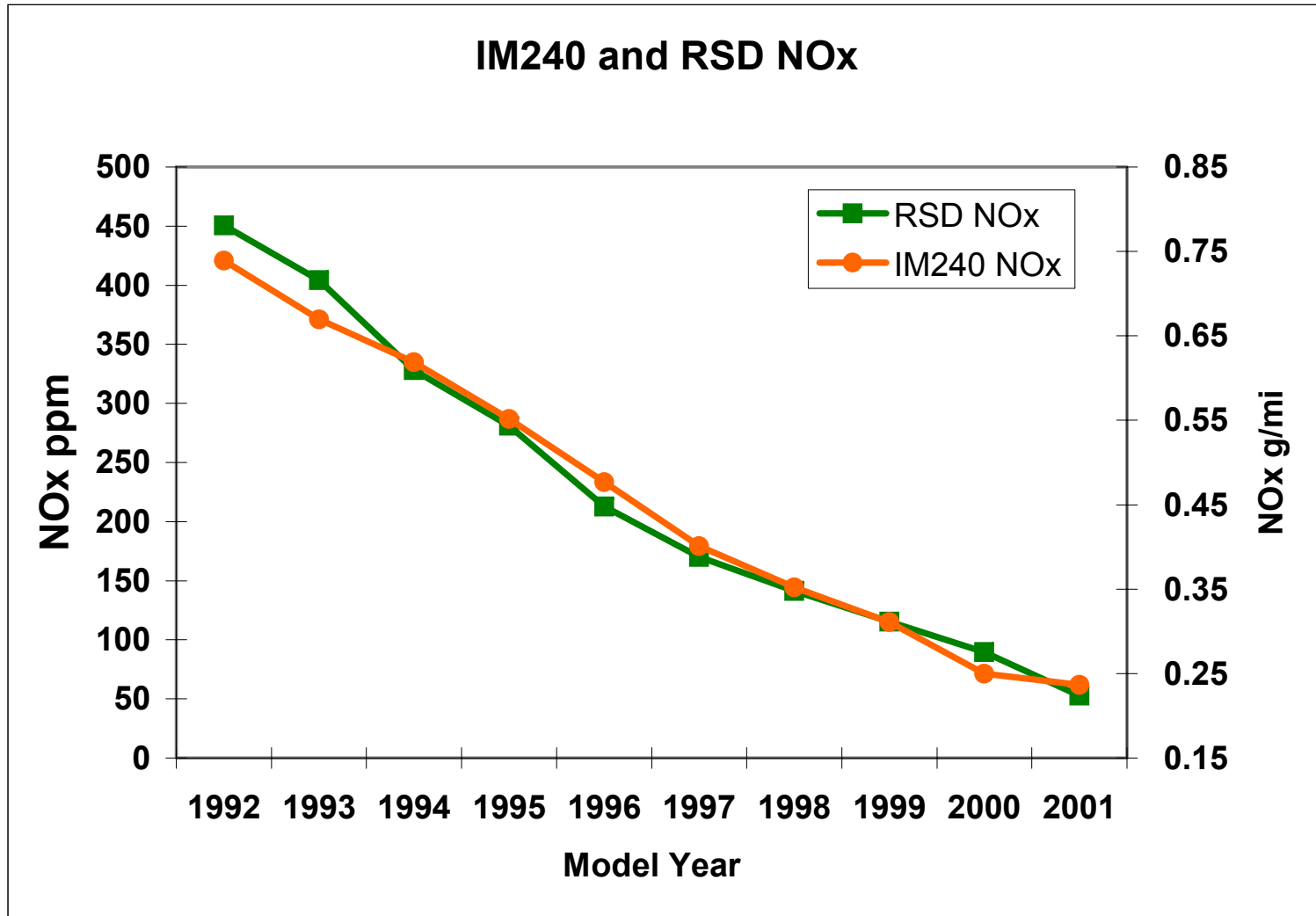


# RSD and I/M 240 - CO





# RSD and I/M 240 - NOx





# Getting the Emissions Picture N=1,000







# Getting the Emissions Picture N=10,000





# Getting the Emissions Picture N=100,000





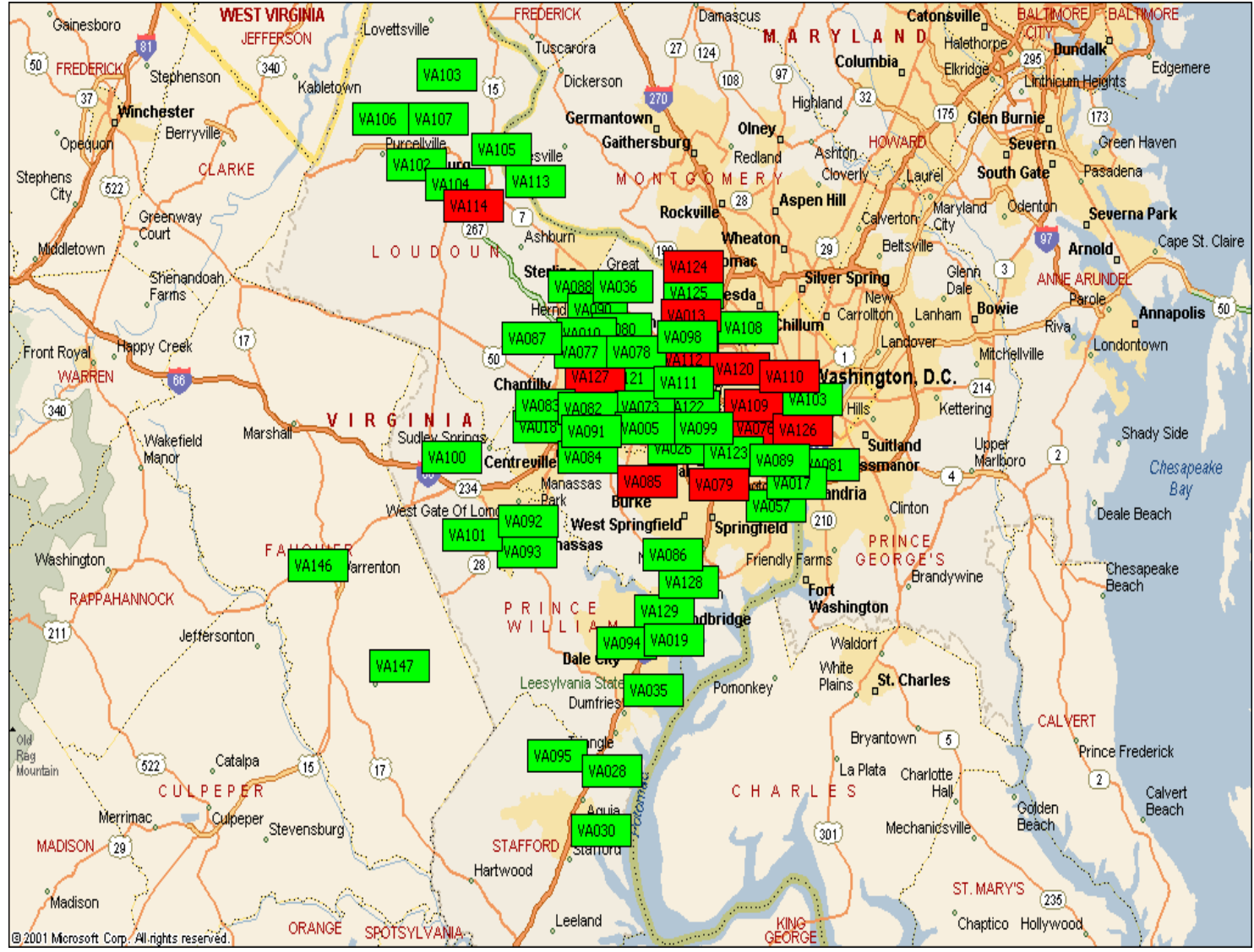
# Vehicle Emissions Picture N=1,000,000





# Northern Virginia I/M Area Sites

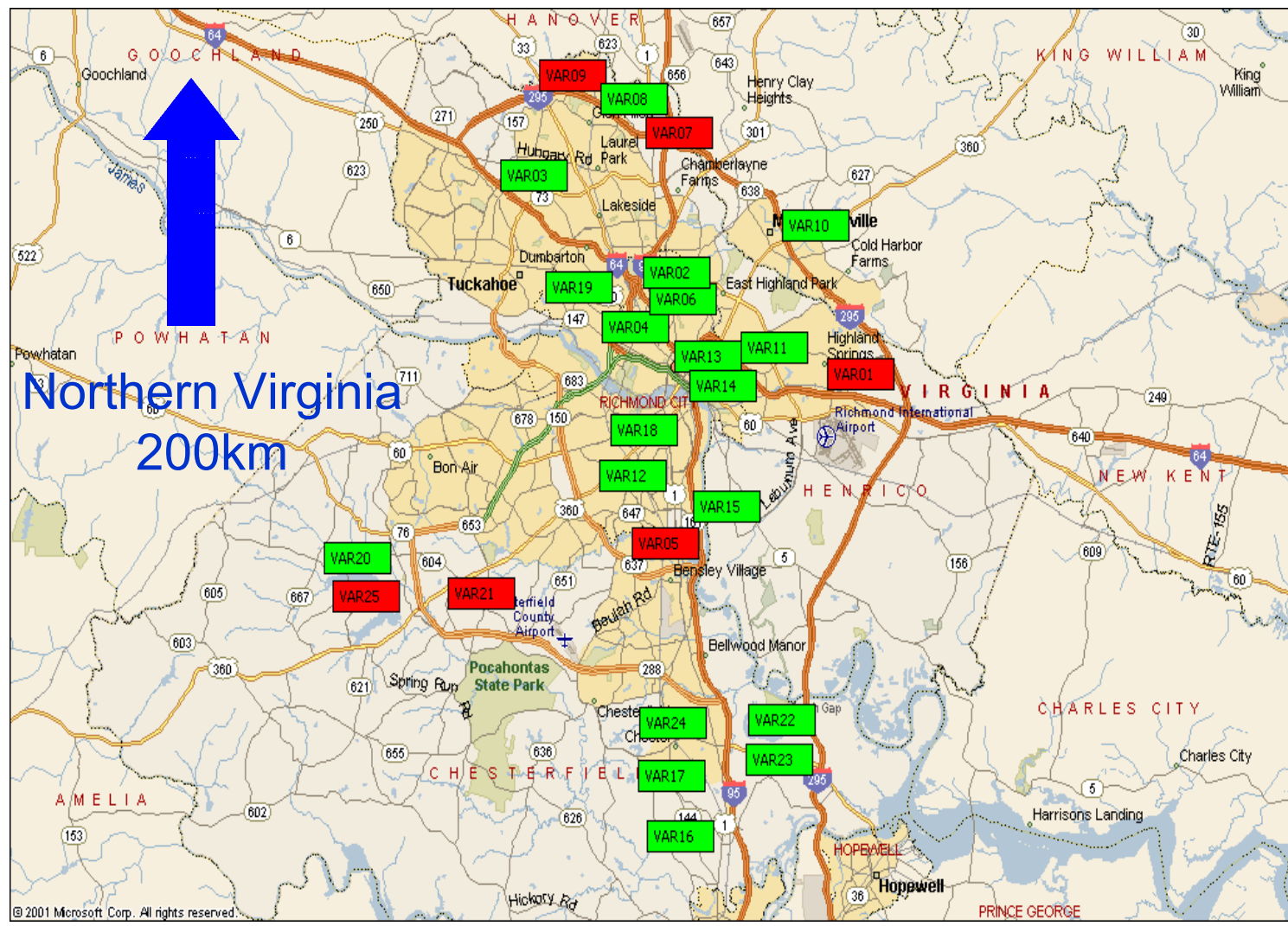
“Metro DC”



© 2001 Microsoft Corp. All rights reserved.



# Richmond non-I/M Area Sites





# Collection Summary

	Measured in I/M Program Area	Measured in Non-I/M Area*	Out of State	Total
Total Number of RSD Units Vans Utilized				2
Total Number of Sites Utilized	59	23	N/A	82
Total Number of Data Collection-Days Readings Taken	193	58	N/A	251
Total Number of Readings Taken	844,740	215,726	N/A	1,060,466
Total Number of Valid Readings Taken	466,125	140,760	73,756	680,641
Total Number of Readings With Readable License Plates	624,050	183,241	97,554	904,845
Total Number of Readings With LPs Not-in-picture, obscured or unreadable	220,690	32,485	N/A	253,175
Total Number of Unique Vehicles Identified	393,172	128,941	75,354	597,467
Total Number of Vehicles Identified Once	252,224	90,905	58,636	401,765
Total Number of Vehicles Identified Twice	87,153	27,199	12,740	127,092
Total Number of Vehicles Identified Three Times	31,420	7,299	2,705	41,424
Total Number of Vehicles Identified Four or More Times	22,375	3,538	1,273	27,186
Total VA Registered Fleet*	1,717,437	928,477	N/A	
% of registered fleet measured	23%	14%		

\* Registrations for Non-I/M Area Counties in Study



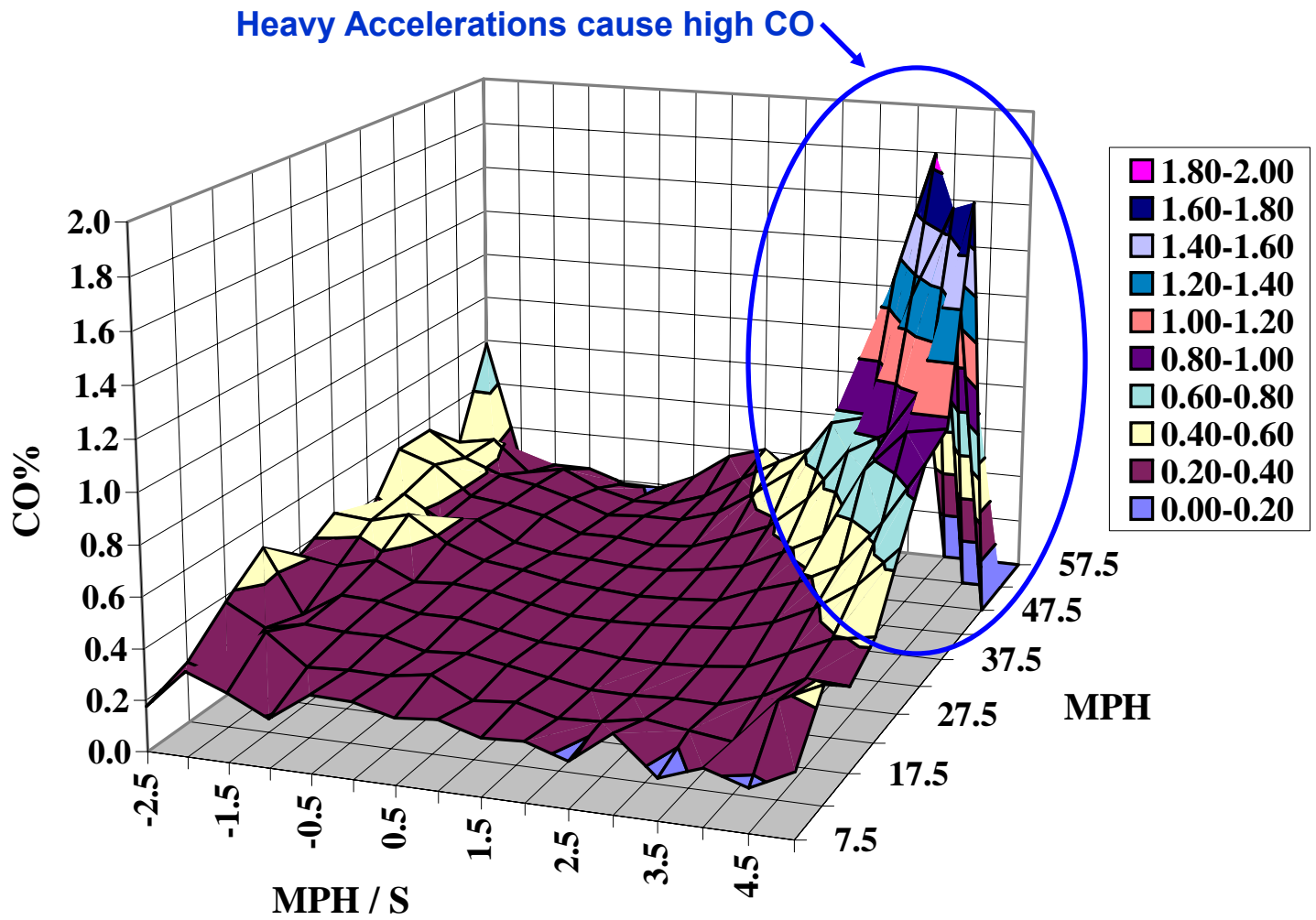
# Data Screening

Vehicle, System, Operator, Driver

1. Screening of exhaust plumes (4000 software criteria)
  - a. Software invalidates small, uncharacteristic plumes
2. Screening of hourly observations to check for cold starts
3. Screening of high values
4. Screening of day-to-day variations in emissions values
5. Screening for Vehicle Specific Power (VSP) range



# CO % vs. Speed & Acceleration



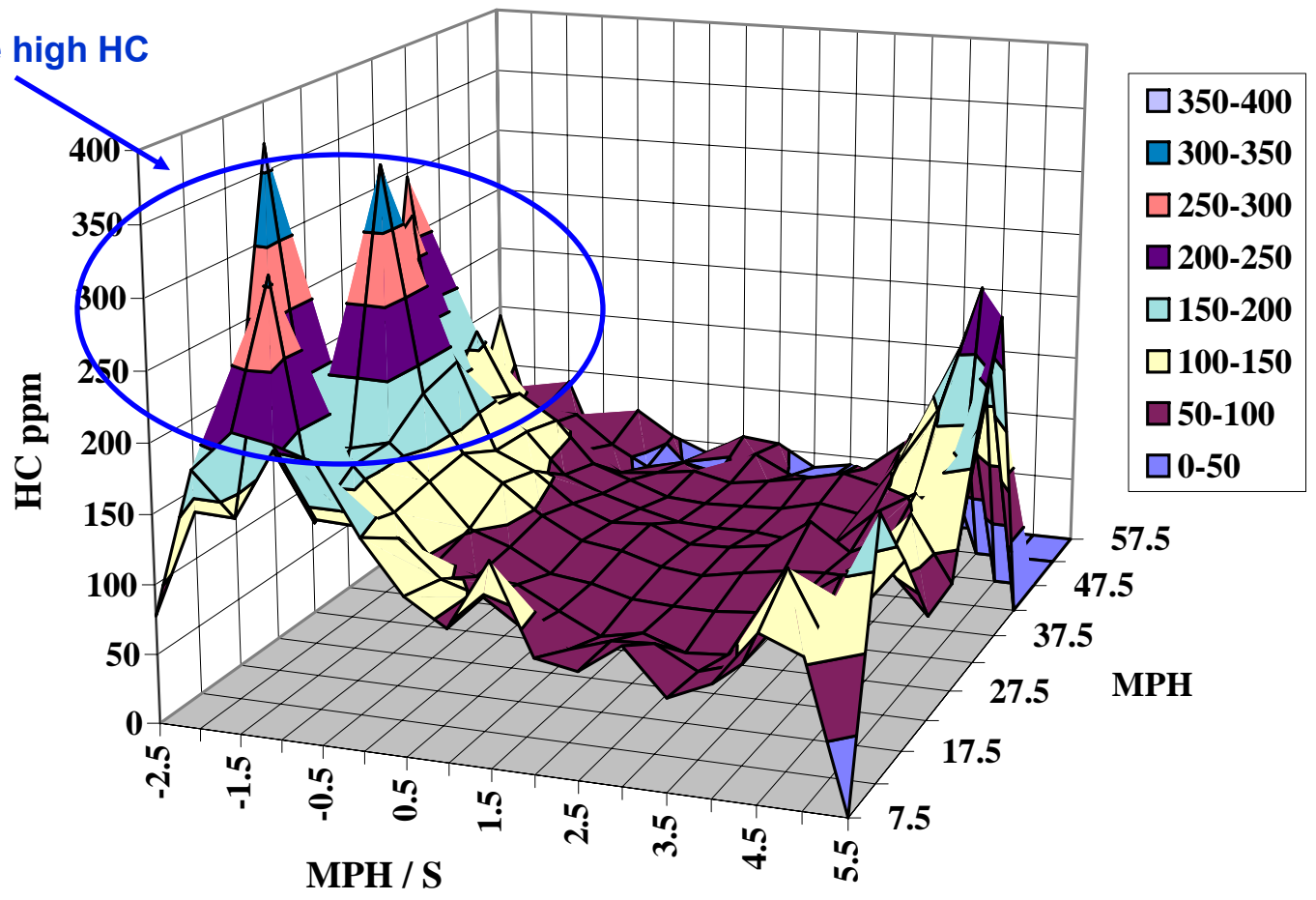
Source: Virginia Remote Sensing Device Study, February 2003





# HC vs. Speed & Acceleration

Decelerations cause high HC

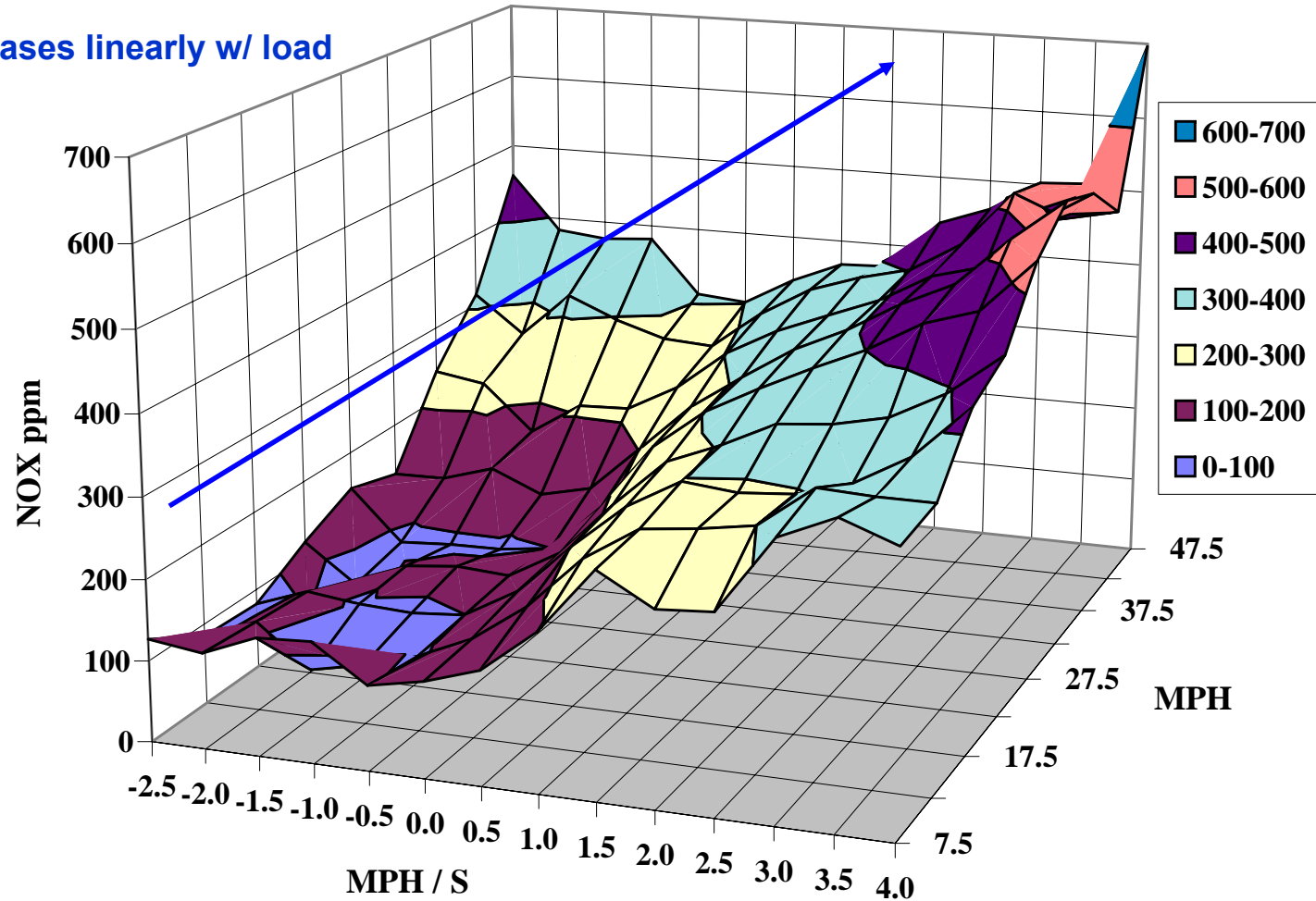


Source: Virginia Remote Sensing Device Study, February 2003



# NOx vs. Speed & Acceleration

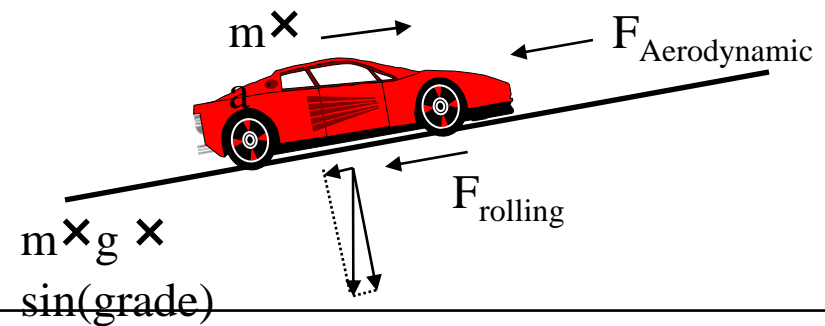
NOx increases linearly w/ load



Source: Virginia Remote Sensing Device Study, February 2003



# Vehicle Specific Power (VSP)



$$\begin{aligned}
 \text{VSP} &= \frac{\text{Power}}{\text{Mass}} = \frac{\frac{d}{dt} (E_{\text{Kinetic}} + E_{\text{Potential}}) + F_{\text{Rolling}} \cdot v + F_{\text{Aerodynamic}} \cdot v + F_{\text{internal friction}} \cdot v}{m} \\
 &\approx v \cdot a \cdot (1 + \epsilon_i) + g \cdot \text{grade} \cdot v + g \cdot C_R \cdot v + \frac{1}{2} \rho_a C_D \frac{A}{m} (v + v_w)^2 \cdot v + C_{\text{if}} \cdot v = \\
 &\approx 1.1 \cdot v \cdot a + 9.81 \cdot \text{grade} \cdot v + 0.213 \cdot v + 0.000305 \cdot (v + v_w)^2 \cdot v
 \end{aligned}$$

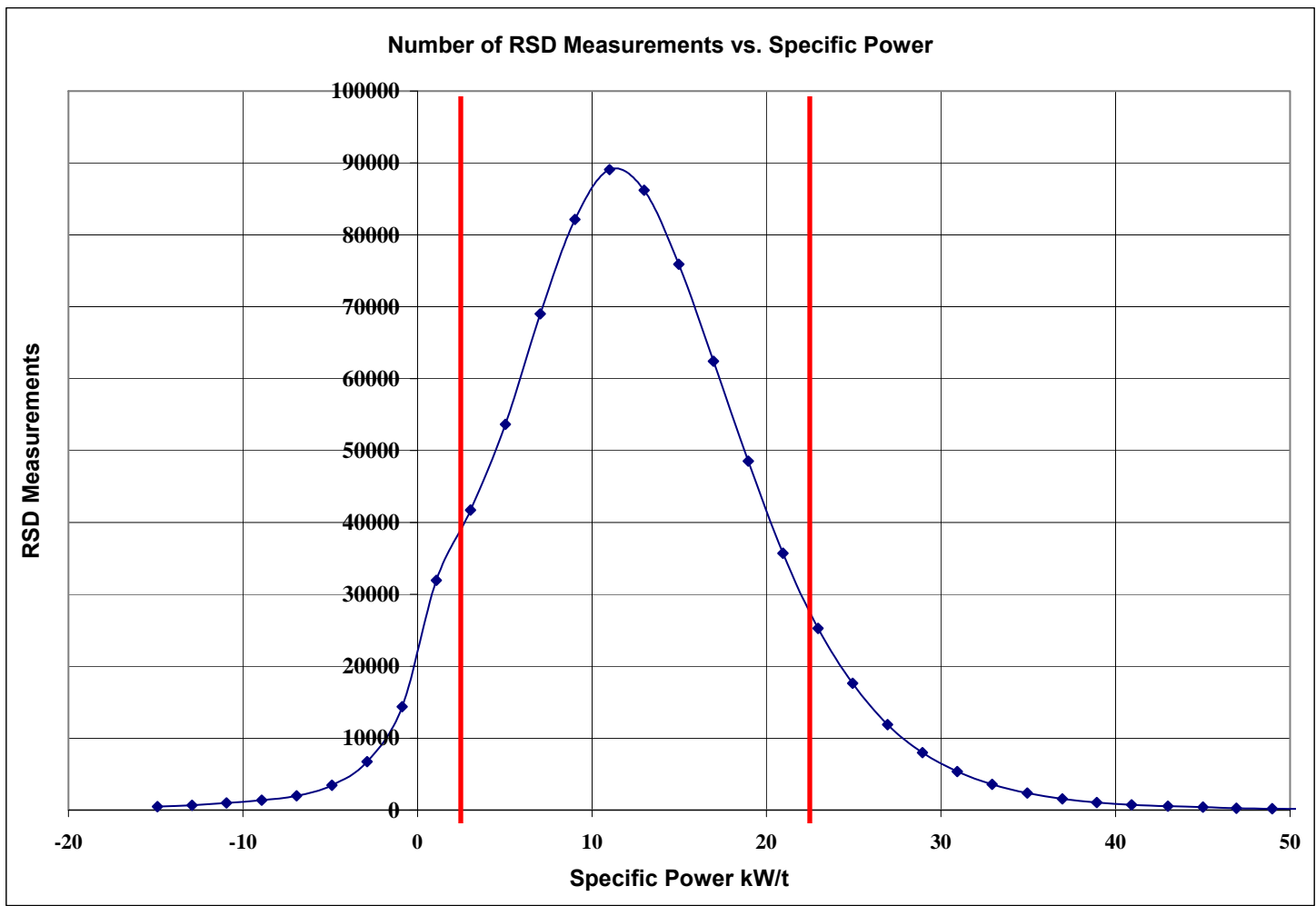
Previous Work:

- Specific Power =  $2 \times v \times a$  (EPA, 1993)
- Positive Kinetic Energy =  $\sum \text{pos}(\text{SP}_i) / \sum \text{distance}$  (Watson et al., 1983)
- DPWRSUM =  $\sum |\text{SP}_i - \text{SP}_{i-1}|$  (Webster and Shih, 1996)



# VSP Screen

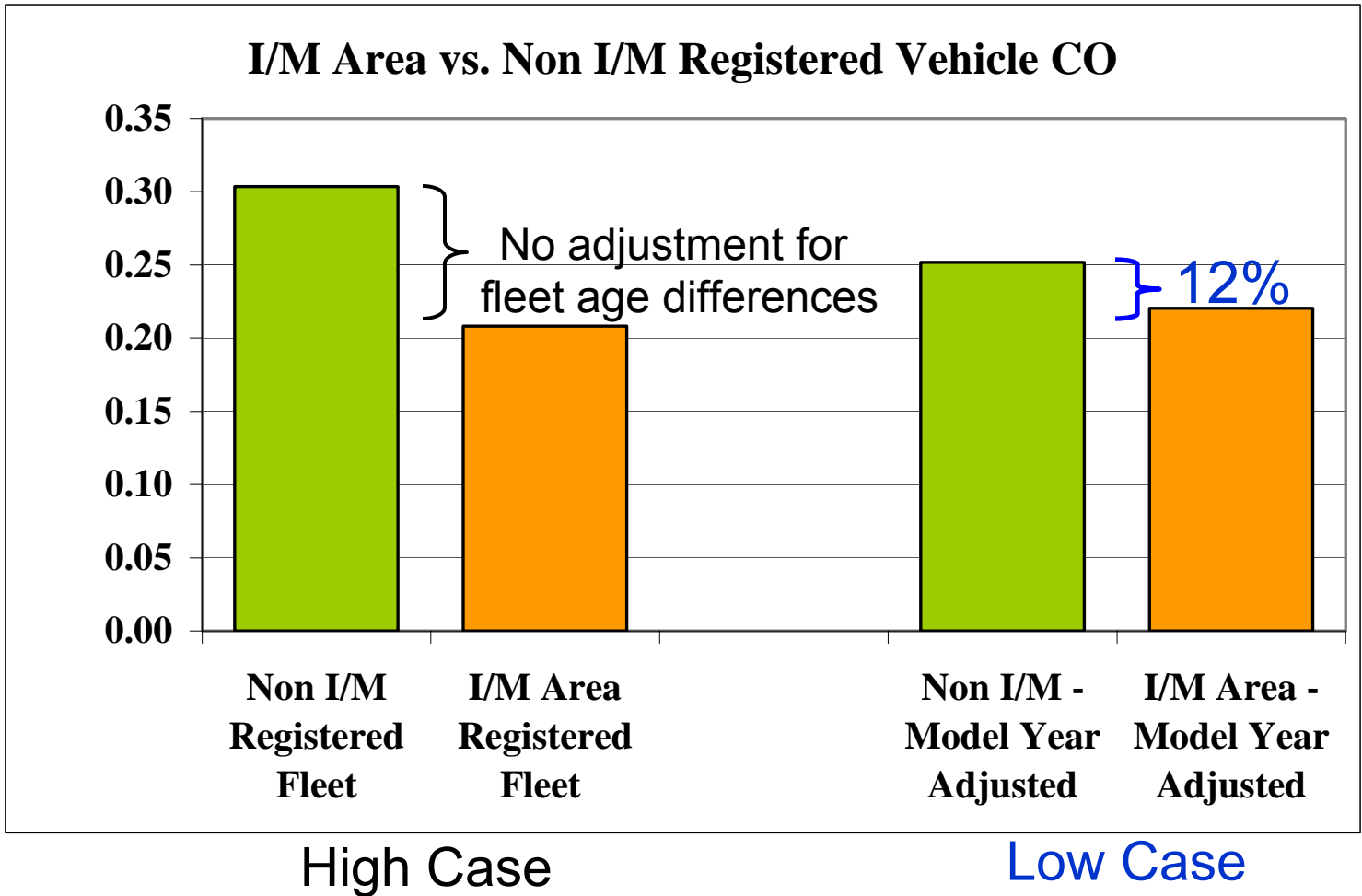
3-22 KW/T





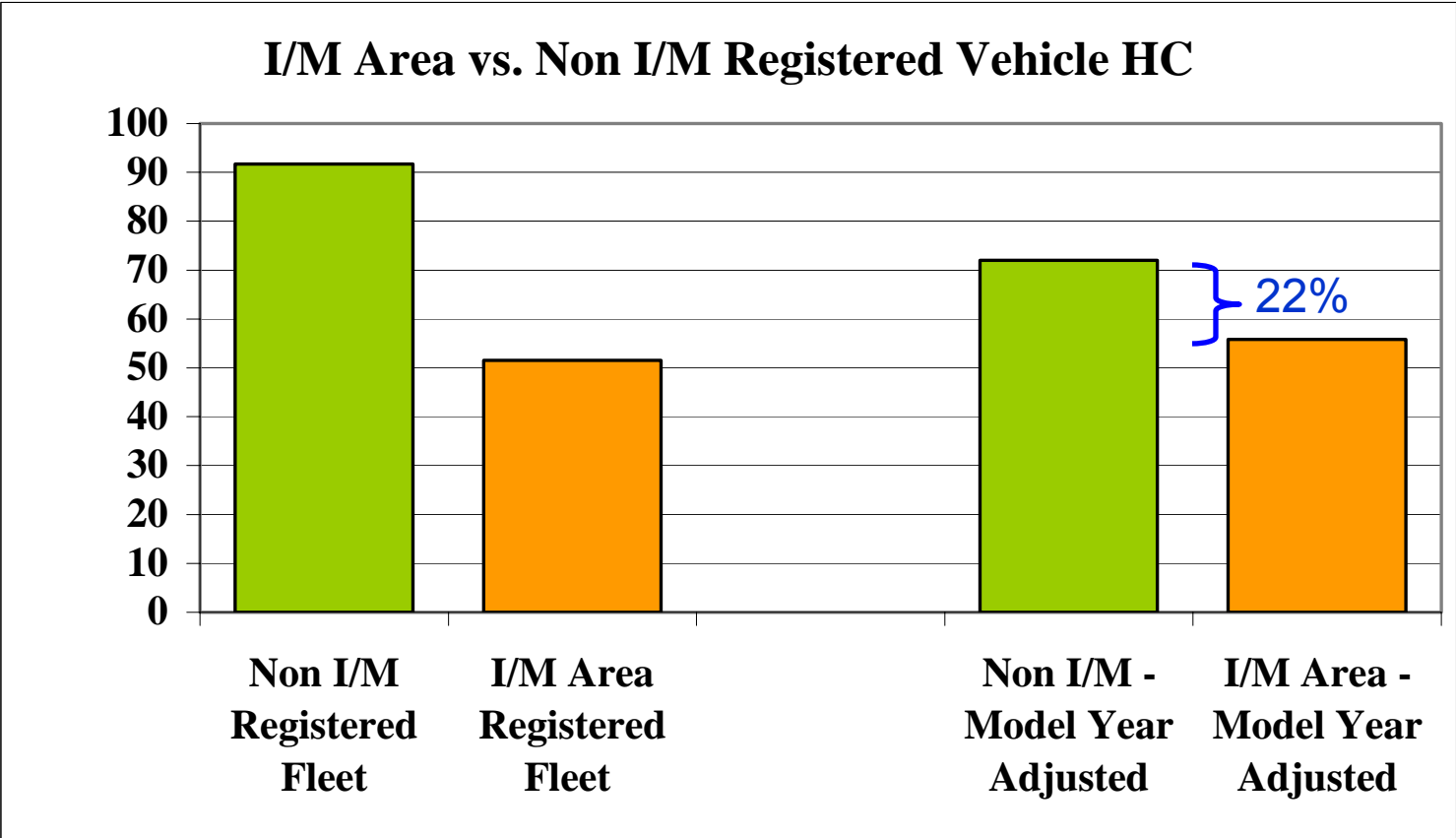
# I/M vs. Non-I/M Emission Rates

## Reference Analysis



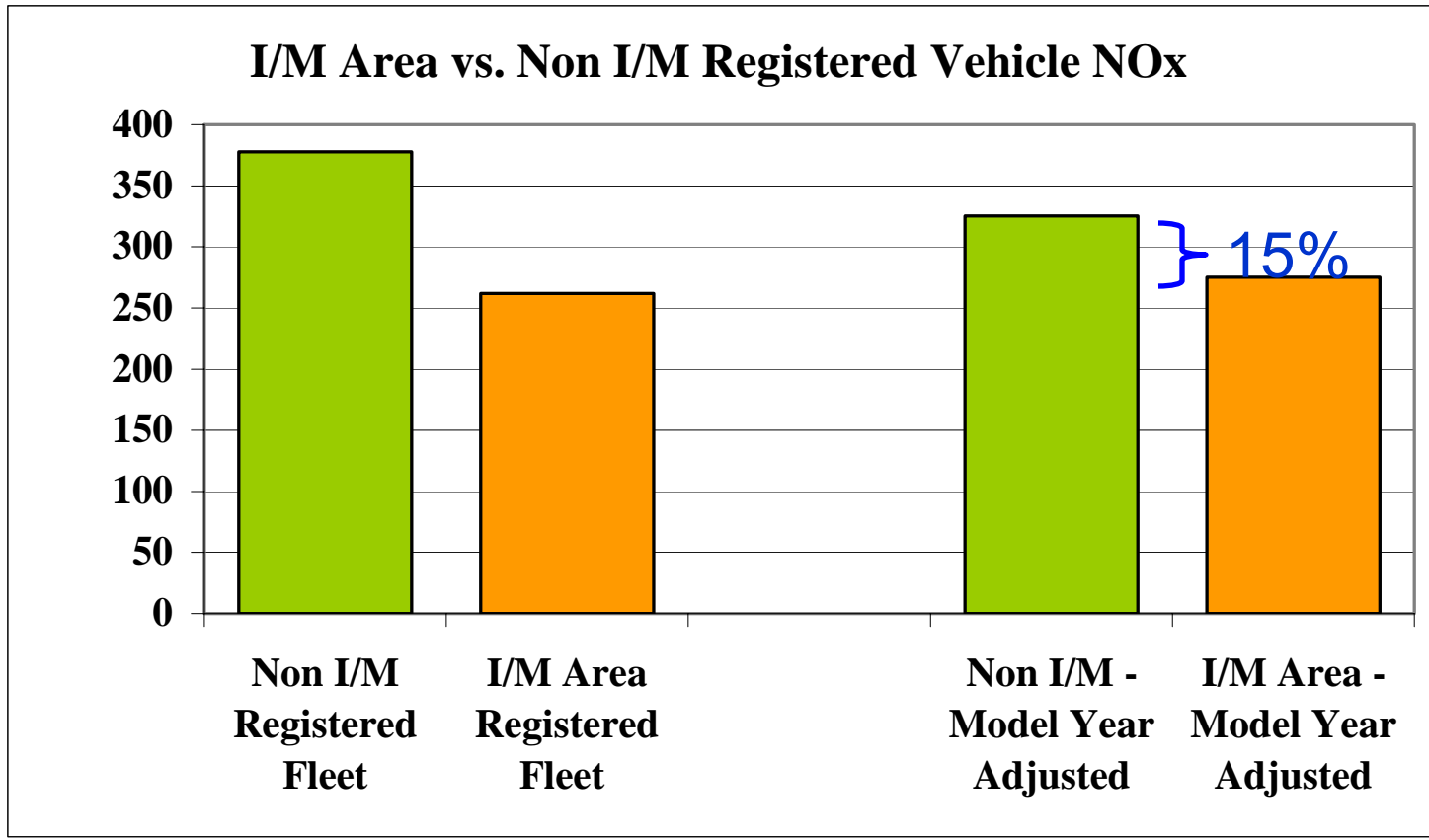


# I/M vs. Non-I/M Emission Rates





# I/M vs. Non-I/M Emission Rates



[Back to Performance Summary](#)

# Heavy Duty Diesel Measurements

“Demonstrated Performance”



August 04







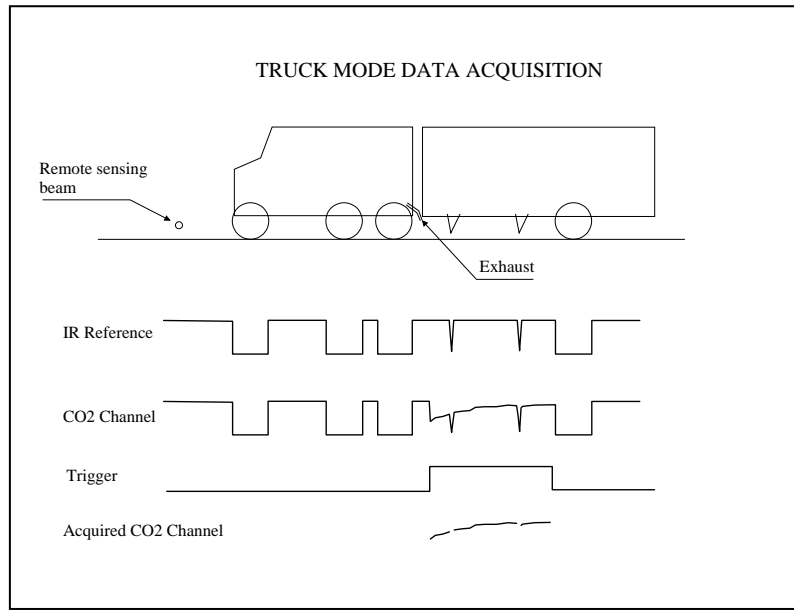
# HD Diesel Measurement Technology

- Today:
- CO<sub>2</sub> - NDIR
  - NO, Smoke Factor - DUV

- Future:
- NO<sub>2</sub> – DUV
  - SO<sub>2</sub>- DUV

High Pipe

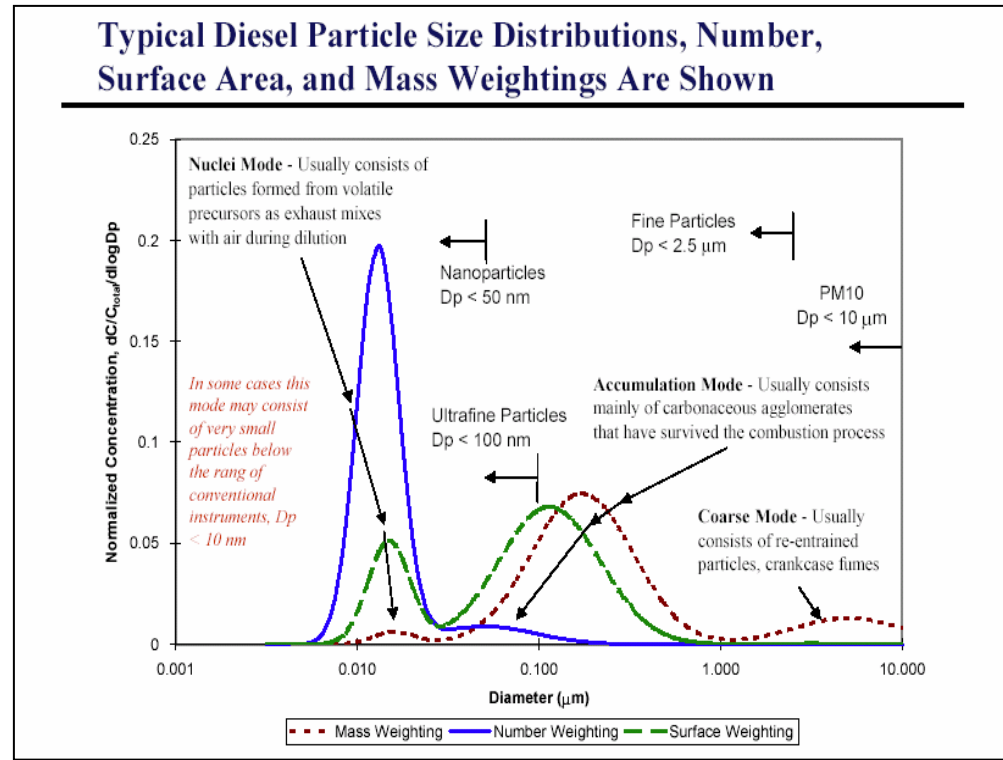
Low Pipe





# Modern Diesel Particle Size

- Classical smoke meters use visible “green” light of ~550 nm. Particles much smaller than 550 nm will be practically invisible; the smoke meter will not sense them!
- Diesel technology >20+ years past: diesel particle sizes mostly larger than 550 nm (mass peak at ~1500nm).
- Diesel technology <20 years past: diesel particle sizes mostly less than 550 nm (mass peak at ~250 nm).

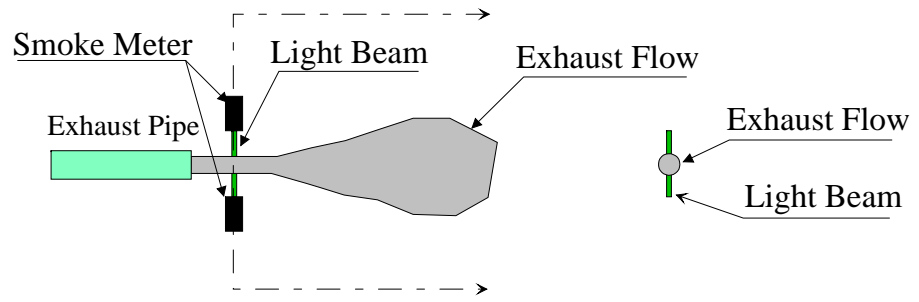


Source: Presentation by David Kittleson, University of Minnesota, Department of Mechanical Engineering, et al “Chemical & Physical Characteristics of Diesel Aerosol,” presented at the 12th Annual CRC Conference, April 15-17, 2002.



# Standard Smoke Meter

## Standard Smoke Meter (light beam passes through entire smoke column)



### Defining Relationship

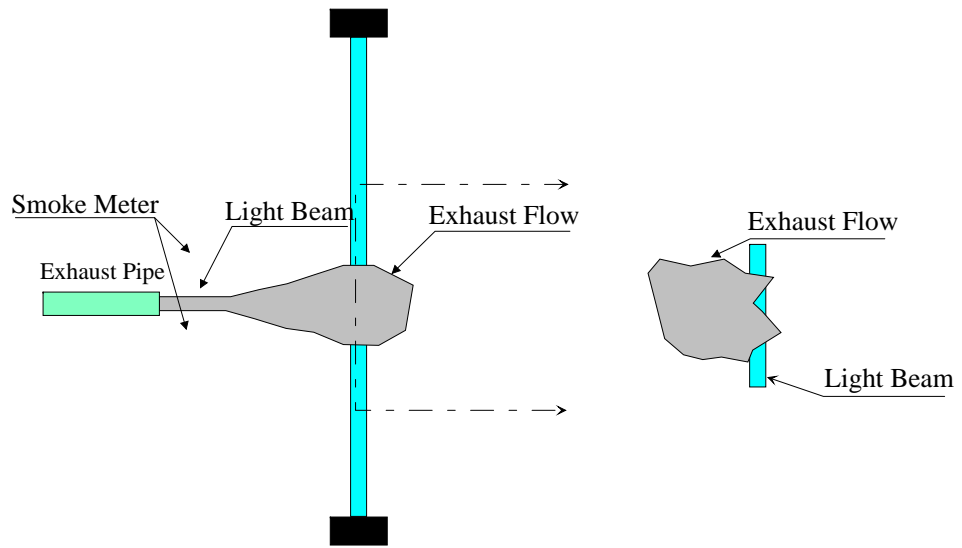
$$T_{gl} := e^{-K_{gl} \cdot N_{smk\_total}}$$

- $T_{gl}$  Green light transmittance (1-opacity) measurement.
- $K_{gl}$  Apparent cross-sectional size per particle at green light wavelength.
- $N_{smk\_total}$  Total number of smoke particles per unit cross-section.



# RSD Smoke Factor

## Remote Sensing Smoke Measurement (light beam passes through a portion of smoke column)



### Defining Relationship

$$T_{uv} := e^{-K_{uv} \cdot N_{smk\_frac}}$$

$$N = [-\ln(T)]/K$$

$T_{uv}$	UV transmittance (1-opacity) measurement
$K_{uv}$	Apparent cross-sectional size per particle at UV wavelength.
$N_{smk\_frac}$	The number of smoke particles per unit cross-sectional area; a fraction of total.



# Our Smoke Number

(a value proportional to number of exhaust smoke particles per unit fuel)

$$SF := \frac{-100 \cdot \ln(T_{uv})}{N_{CO2\_frac} + N_{CO\_frac} + N_{HC\_frac}}$$

where

$N_{CO2\_frac}$  is amount of plume CO<sub>2</sub> in %-cm

$N_{CO\_frac}$  is amount of plume CO in %-cm

$N_{HC\_frac}$  is amount of plume HC in %-cm

# Sulfur Dioxide Remote Sensing in Vehicle Exhaust

Daniel A. Burgard, Gary A. Bishop, and Donald H. Stedman  
 Department of Chemistry and Biochemistry  
 University of Denver

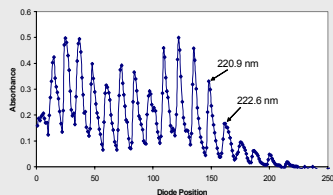
## Sulfur in Fuel

- Current caps in US Fuel
  - Gasoline 300 ppm (CA 80 ppm)
  - On-road Diesel 500 ppm
  - Off-Road Diesel 5000 ppm
- Europe has a 500 ppm cap on gasoline with a zero sulfur (10 ppm) proposal
- New Zealand on-road diesel contains 1800 ppm
- Iran on-road diesel contains 5000 ppm
- Why is Sulfur in Fuel bad?
  - Produces sulfur dioxide in exhaust
  - Poisons catalysts in emission control systems
- High sulfur fuel is still used
  - There is a cost to get rid of sulfur in fuel
  - There is an economic incentive for its use for example
    - Off-road diesel used on road
    - Untaxed high sulfur fuel brought across the border in Hong Kong

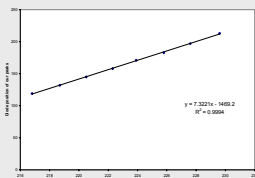
## Remote Sensing

- Detecting SO<sub>2</sub> in the exhaust of vehicles is informative for both pollution and sulfur in fuel content.
- Our current Fuel Efficiency Automobile Test (FEAT) was adapted to measure the UV absorption of SO<sub>2</sub>.

SO<sub>2</sub> Spectra Collected from a FEAT 3000 Unit



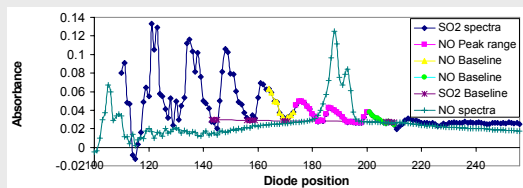
Sulfur Peak Validation



Pearse, R.W.B. and Gaydon, A.G. The Identification of Molecular Spectra 3rd ed.: The Whitefriars Press, Ltd., 1963, p 268-9.

## SO<sub>2</sub> Software

- Current FEAT software had to be adapted to include SO<sub>2</sub> detection.
- FEAT measures NO in the UV range at 226 nm.
- SO<sub>2</sub> peaks at 220.9 nm and 222.6 nm are used for detection.

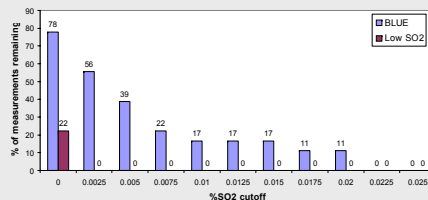


## Road Tests

- Our 1985 Chevrolet Celebrity Station Wagon "BLUE" had dimethyl sulfoxide added to the gas tank to reach a sulfur in fuel content of 2000 ppm.
- This car was then driven around a parking lot in front of a FEAT 3000 unit.
- A 2002 Honda Accord was driven around the parking lot in front of the same remote sensor.



## LEV Honda Comparison to the Sulfur Doped Car to Establish an SO<sub>2</sub> Cutoff



## Variable Sulfur Amounts in On Road Emissions

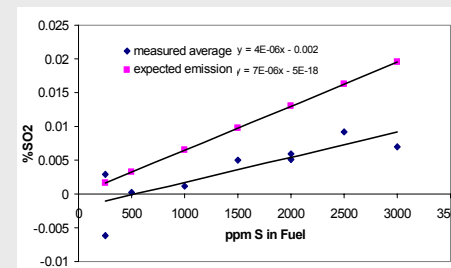
- The fuel line from the Chevy Celebrity's fuel tank was disconnected and an auxiliary fuel tank was attached to the roof of the car.
- This provided an easy way to quickly switch fuel.
- One liter samples of varying sulfur doped gasoline were made and used in a parking lot study.

October 2002

## Expected SO<sub>2</sub> in Exhaust

- $CH_2 + S + 1.5(O_2 + 4N_2) > CO_2 + H_2O + 6N_2 + SO_2$
- 1000 ppm by weight S = 10<sup>-3</sup> g S/ g Fuel
- 14 g/mole Fuel and 32 g/mole S
- = 4.4 E-4 mole S/ mole Fuel
- = 4.4 E-4 mole S/ mole CO<sub>2</sub>
- 4.4 E-4 mole SO<sub>2</sub> will be made for every 1 mole CO<sub>2</sub> and 6 mole N<sub>2</sub>
- 4.4 E-4 mole SO<sub>2</sub> / 7 moles of gas
- ~ 63 ppm by volume SO<sub>2</sub> in exhaust

## Average Emissions of Sulfur Doped Fuel Every 500 ppm



## Conclusions

- By remote sensing, the FEAT unit can catch vehicles using 2000 ppm sulfur in fuel 56% of the time with no false positives by measuring SO<sub>2</sub> emissions.
- By remote sensing, the FEAT unit measures increasing SO<sub>2</sub> emissions with increasing sulfur in fuel.
- Currently we are unable to detect SO<sub>2</sub> at the level expected through calculation, most likely because of interactions with the catalyst.



# NO<sub>2</sub> Measurement

71

- The wavelengths of interest are at 380-400nm.
- Not yet determined if our light sources have adequate intensity at these wavelengths to be useful.

[Back to Performance Summary](#)

# Matching Laboratory Analyzers

## Diesel Vehicles



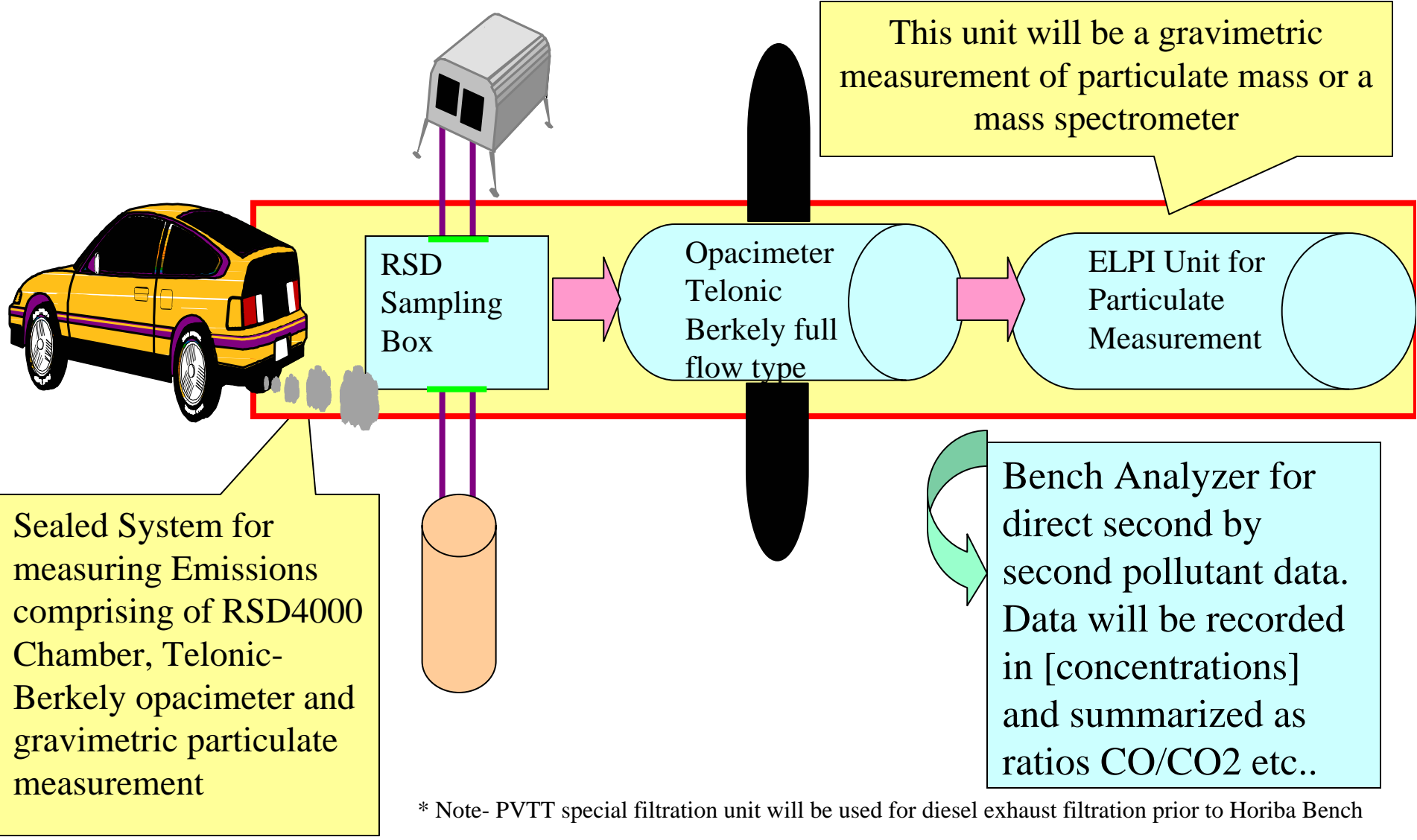
August 04







# Correlation Test Configuration



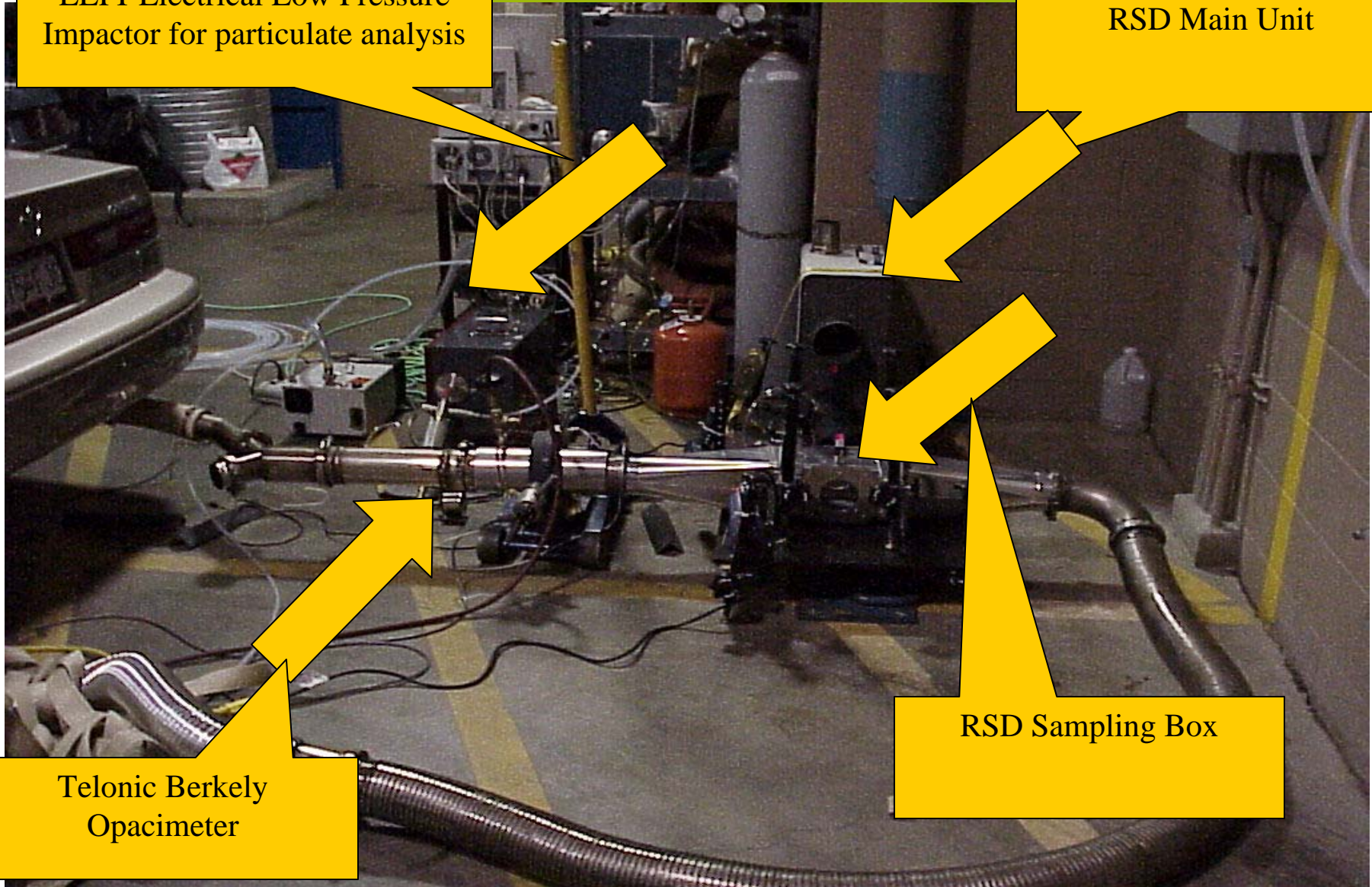
# Test Layout

ELPI-Electrical Low Pressure Impactor for particulate analysis

RSD Main Unit

RSD Sampling Box

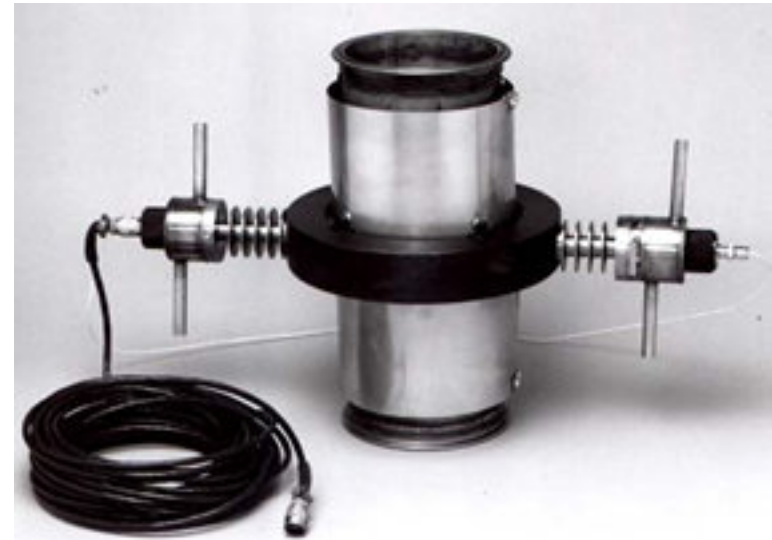
Telonic Berkely Opacimeter





# Equipment and Specifications

- **Telonic-Berkeley Opacimeter**
  - In-line, Full flow
  - + or - 0.5% Accuracy
  - ISO/DIS 11614
  - Euro III
  - EPA 40 CFR 86.884-9
- Meets requirements for diesel engine Federal test cycle
- Measures opacity in the 0-100% range



## ELPI-Electrical Low Pressure Impactor (Dekati)



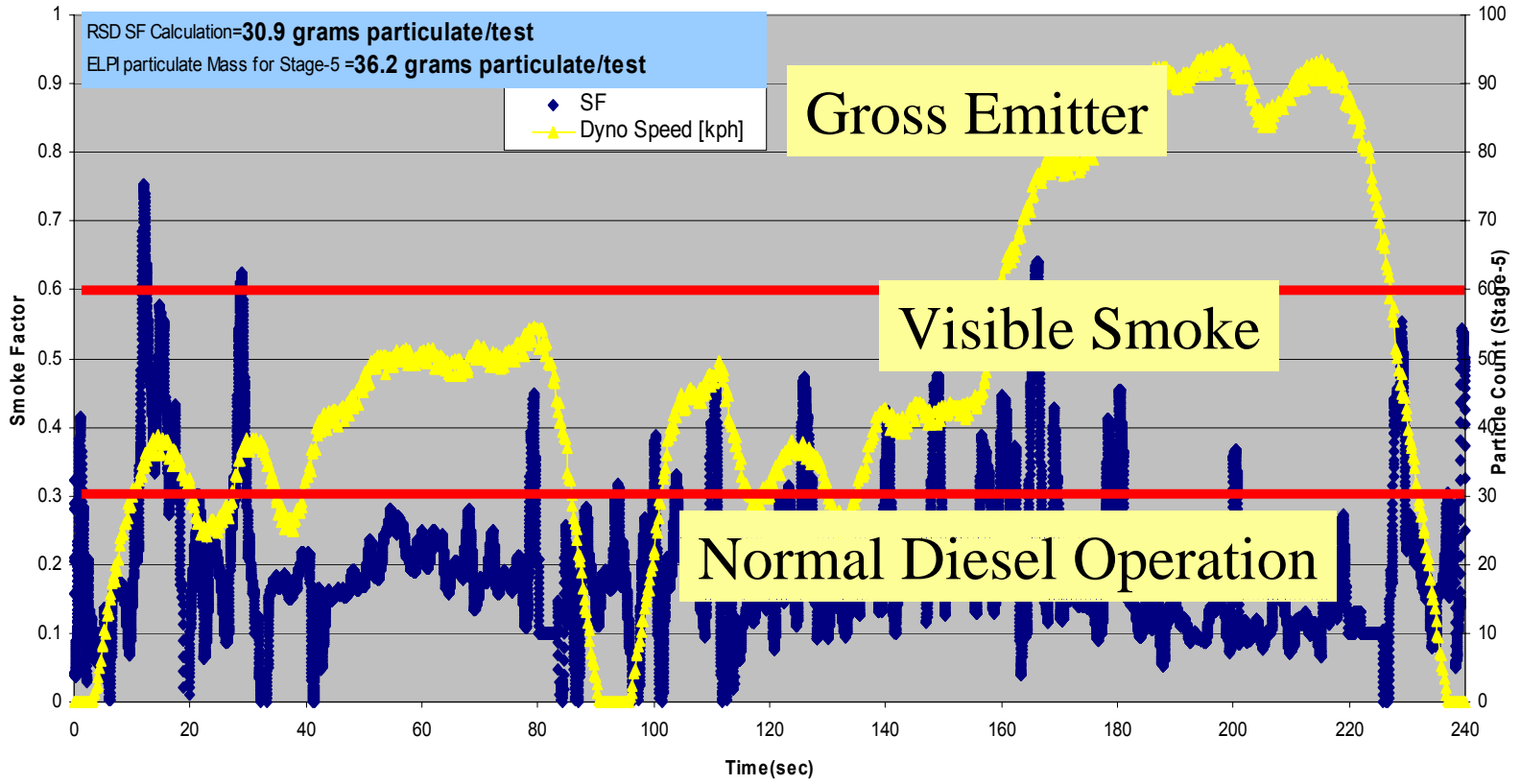
The impactor has 13 successive impactor stages: 10  $\mu\text{m}$ , 6.8  $\mu\text{m}$ , 4.4  $\mu\text{m}$ , 2.5  $\mu\text{m}$ , 1.6  $\mu\text{m}$ , 1.0  $\mu\text{m}$ , 0.65  $\mu\text{m}$ , 0.4  $\mu\text{m}$ , 0.26  $\mu\text{m}$ , 0.17  $\mu\text{m}$ , 0.108  $\mu\text{m}$ , 0.060  $\mu\text{m}$  and 0.030  $\mu\text{m}$ . Particle size distribution is defined by measuring the number of particles impacted on the stages of the cascade impactor.

Particle size range	0.030-10 $\mu\text{m}$ , with filter stage 0.007-10 $\mu\text{m}$
Number of Stages	12 with electrical detection, total 13
Volumetric flow rate	10 or 30 l/min
Impactor dimensions	$\varnothing$ 65 mm x 300 mm
Collection plate diameter	25 mm
Lowest stage pressure	100 mbar
Pump requirements	7 m <sup>3</sup> /h at 100 mbar (10 lpm), 21 m <sup>3</sup> /h at 100 mbar (30 lpm)
Operation temperature	5-40°C
Operation humidity	0-60 % R.H.
Response time	below 5 seconds
ELPI unit dimensions	H 540 x W 400 x D 230 mm
Unit weight	35 kg
Charger voltage	5 kV
Charger current	1 $\mu\text{A}$
Computer requirements	Pentium processor, 16 MB RAM, MS-WINDOWS 95 <sup>TM</sup> , 98 <sup>TM</sup> , NT 4.0 <sup>TM</sup> or 2000 <sup>TM</sup>



# Particulate Correlation to SF - Black Smoke

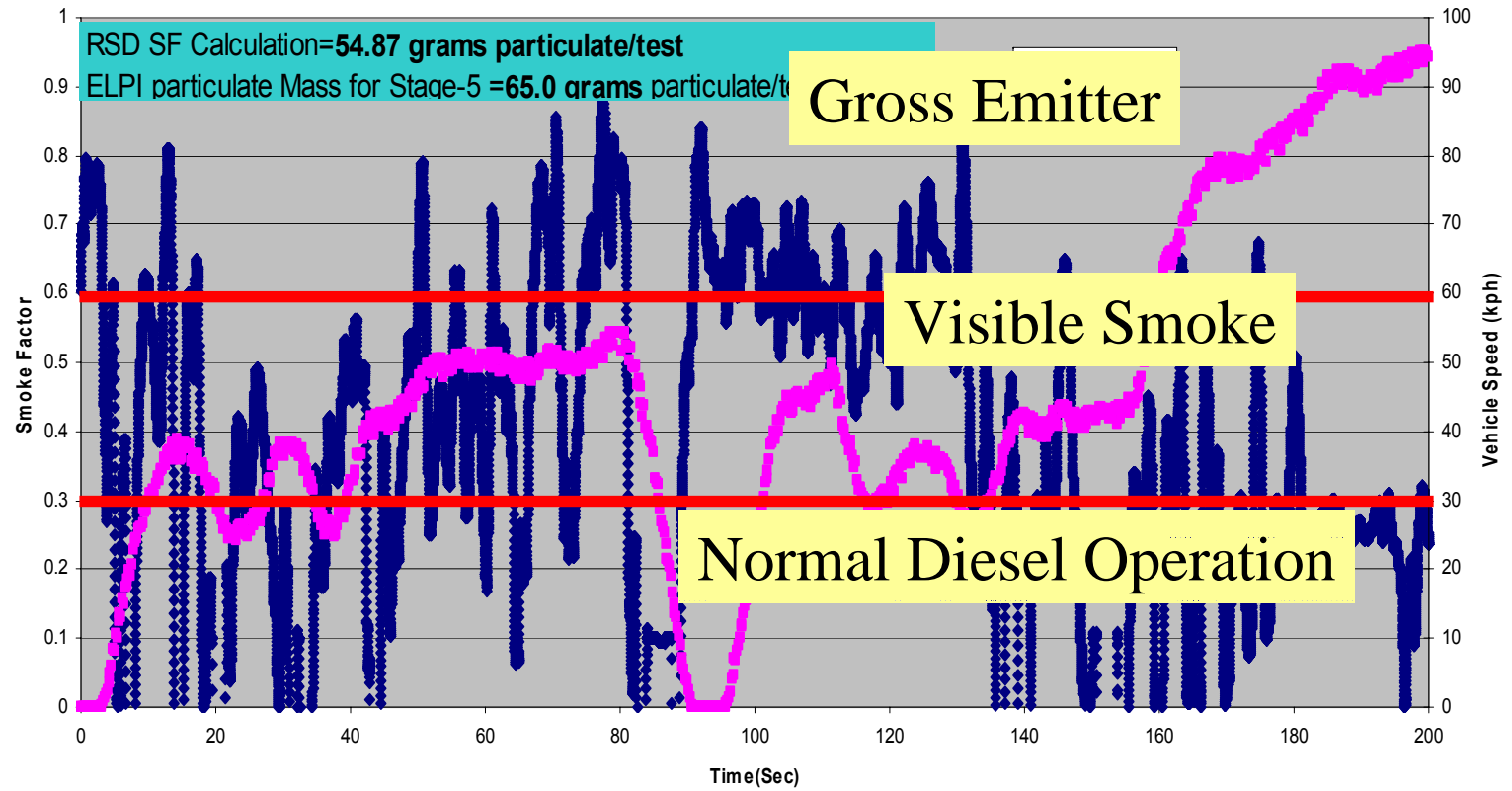
Correlation to Particulate Measurement





# Particulate Correlation to SF - White Smoke

Correlation to Particulate Measurement



[Back to Performance Summary](#)

# Matching Inspection Results



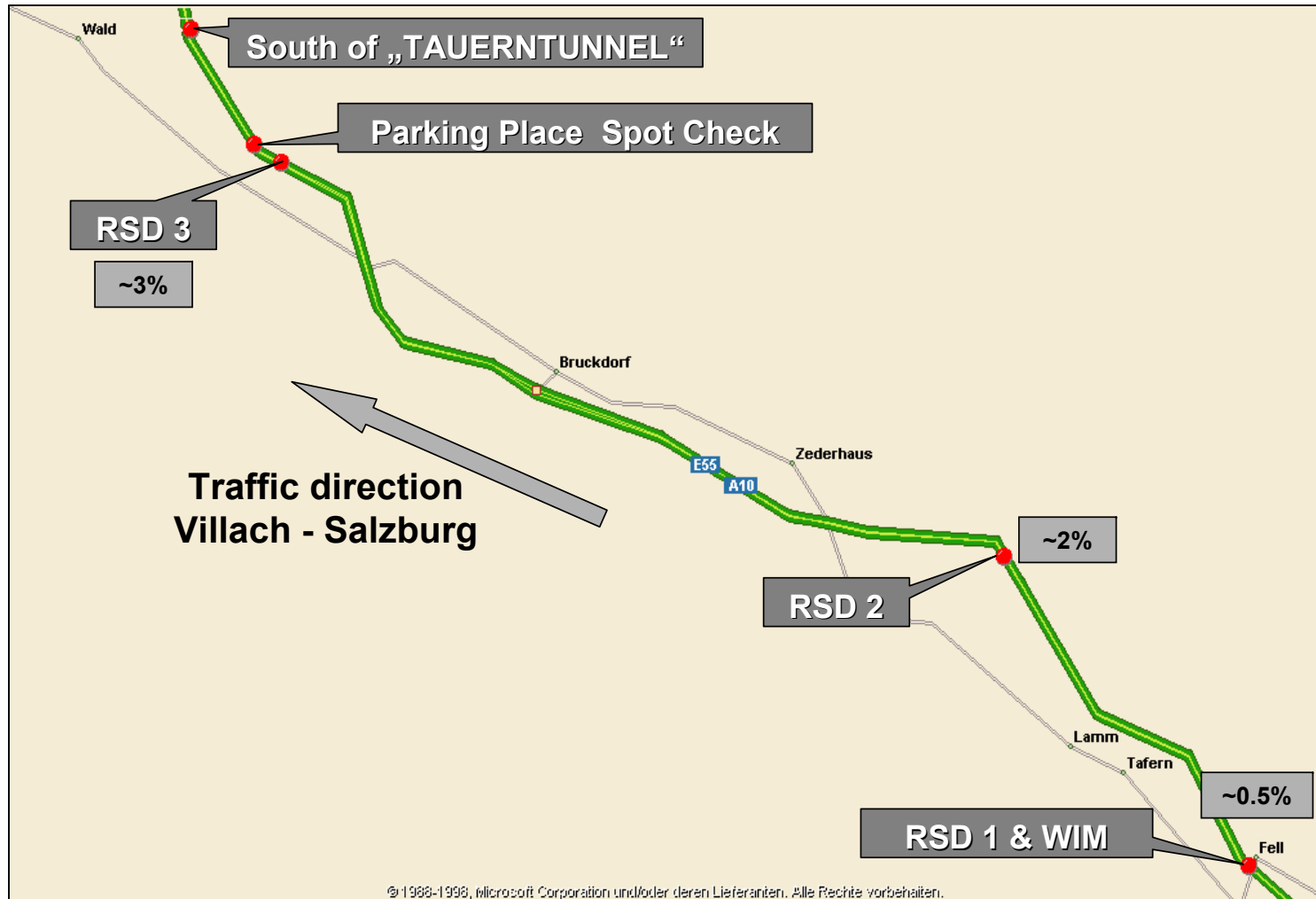
August 04





# NO Correlation Study

BPA & Univ. of Vienna

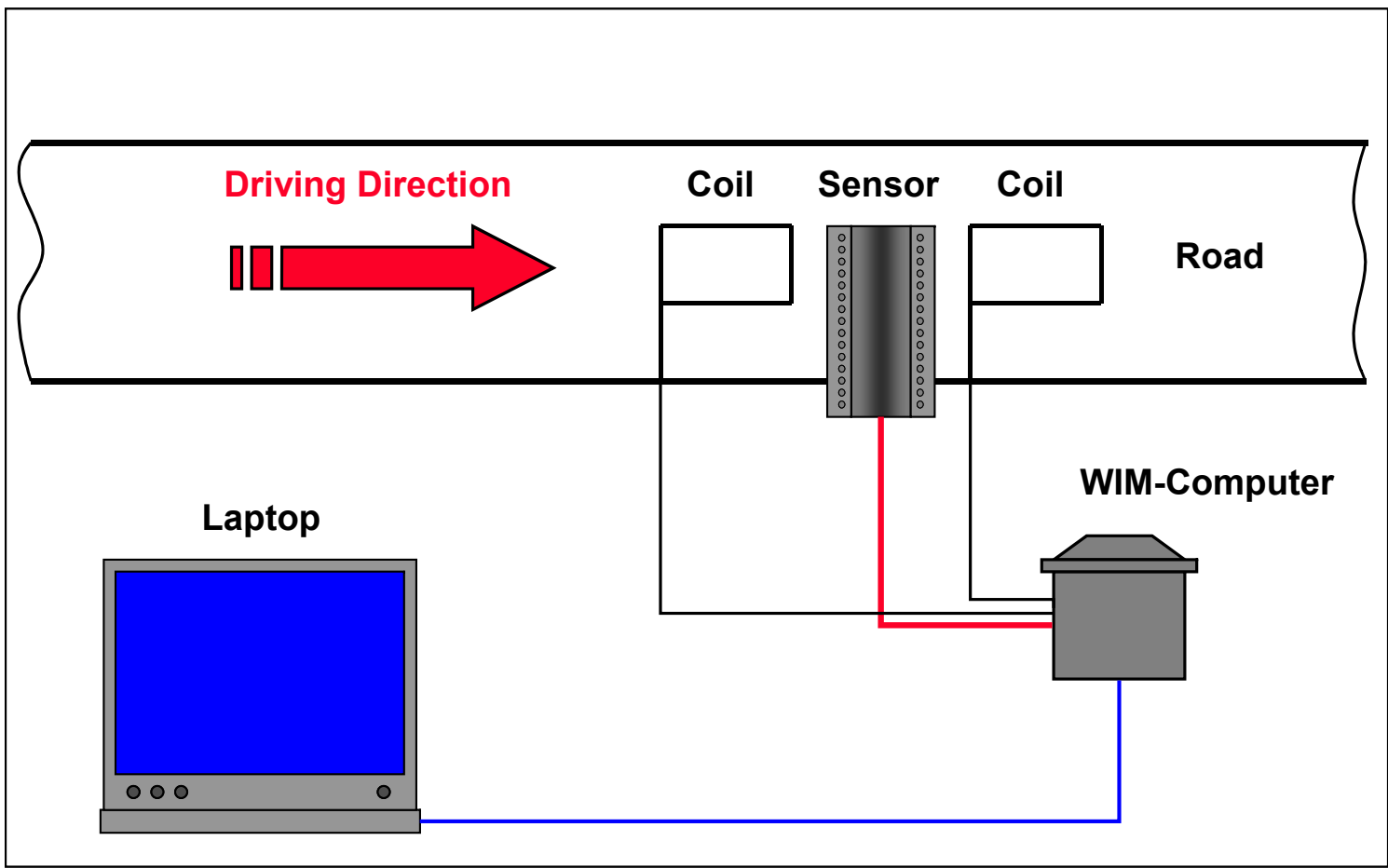






# NO Correlation Study

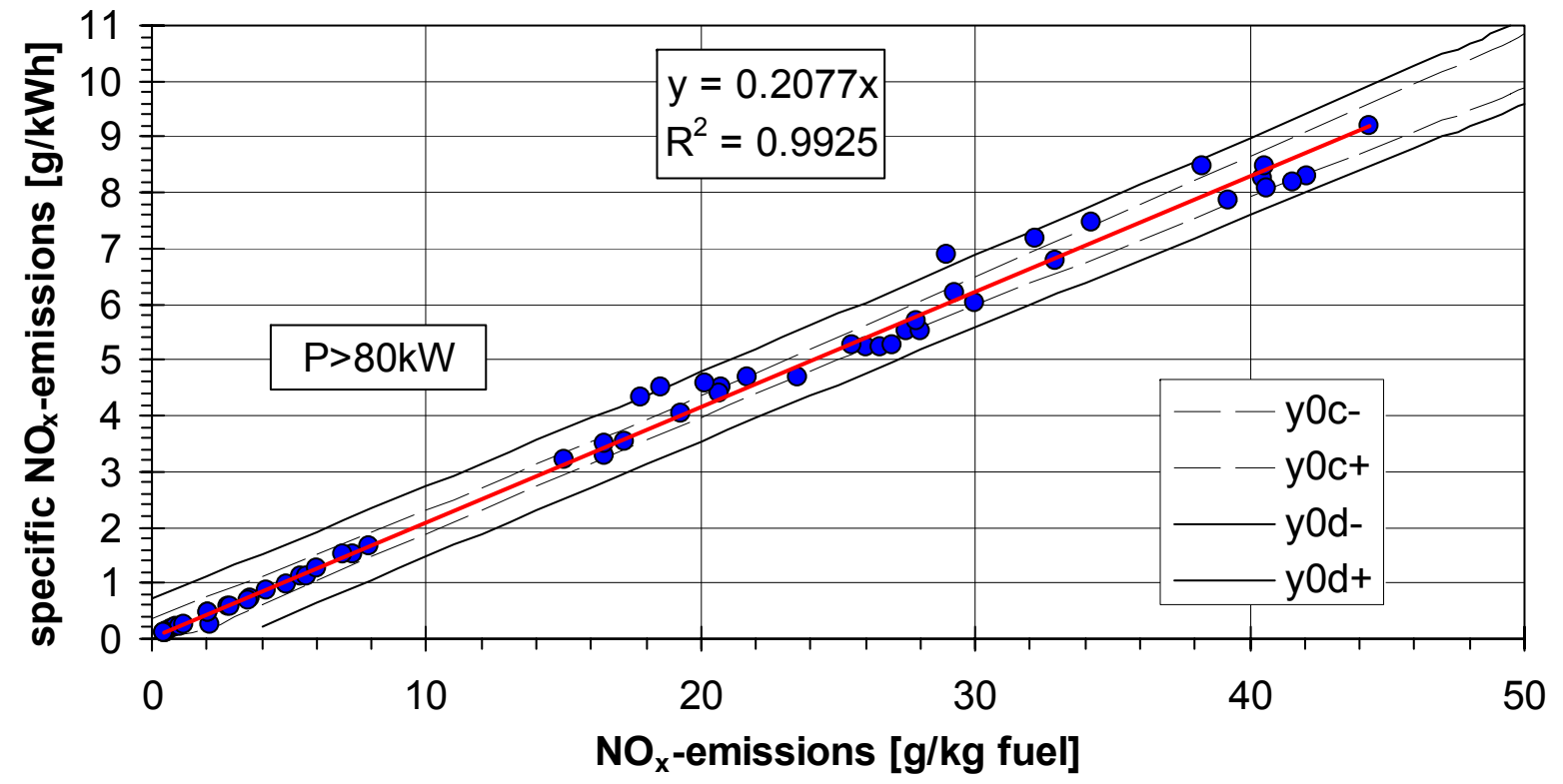
BPA & Univ. of Vienna





# NO Correlation Study

BPA & Univ. of Vienna





# Vancouver Diesel Smoke Study

RSD vs. Lane Opacity - June 2002





# Test Methods Comparison

## RSD Test

- Snap shot (<0.5-sec) of vehicle operating condition.
- Measurement: Fuel specific UV opacity → **opacity/unit fuel**
- Pass/fail: maximum reading of several drive-by's (typically 3).
- Lane operator drove vehicle trying to pass RSD station under varying acceleration, but steady throttle.
- Opacity measurement in **UV** region.
- Measurements include: Smoke Factor, CO, CO<sub>2</sub>, HC, and NO.

## IM147 Test

- Chassis dynamometer test cycle of 147-seconds.
- Opacity (corrected to J1667 exhaust pipe sizes).
- **Peak opacity** during test cycle.
- Lane operator drives vehicle trying to maintain IM147 speed profile. Loads can vary on manual transmissions.
- Opacity measurement in **“green”** visible light region.
- Measurements include: opacity



# RSD Installation

Langley Parking Lot





# RSD Installation

Abbotsford Entry Lane





# Overview of Testing Methods

- Station Lane Test:
  - IM147 (last 147-seconds of IM240 driving cycle) test cycle.
  - Wager full-flow opacity meter, Beer-Lambert corrected opacity.
  - Running average filtering
  - Test value is peak opacity value during test cycle.
  - **Fail limit set to 30%.**
  
- RSD Test:
  - Conducted immediately after lane test.
  - Test reading is maximum of multiple passes (typically 3 passes).
  - Lane inspector drives vehicle
  - Langley (parking lot): accelerate from dead stop; typical speeds (18-25 mph); typical accelerations (0-3.5 mph/second).
  - Abbotsford (entry lane): slight down slope; similar speeds and accelerations to Langley.
  - **Fail Limit of 1.0 on smoke factor.**



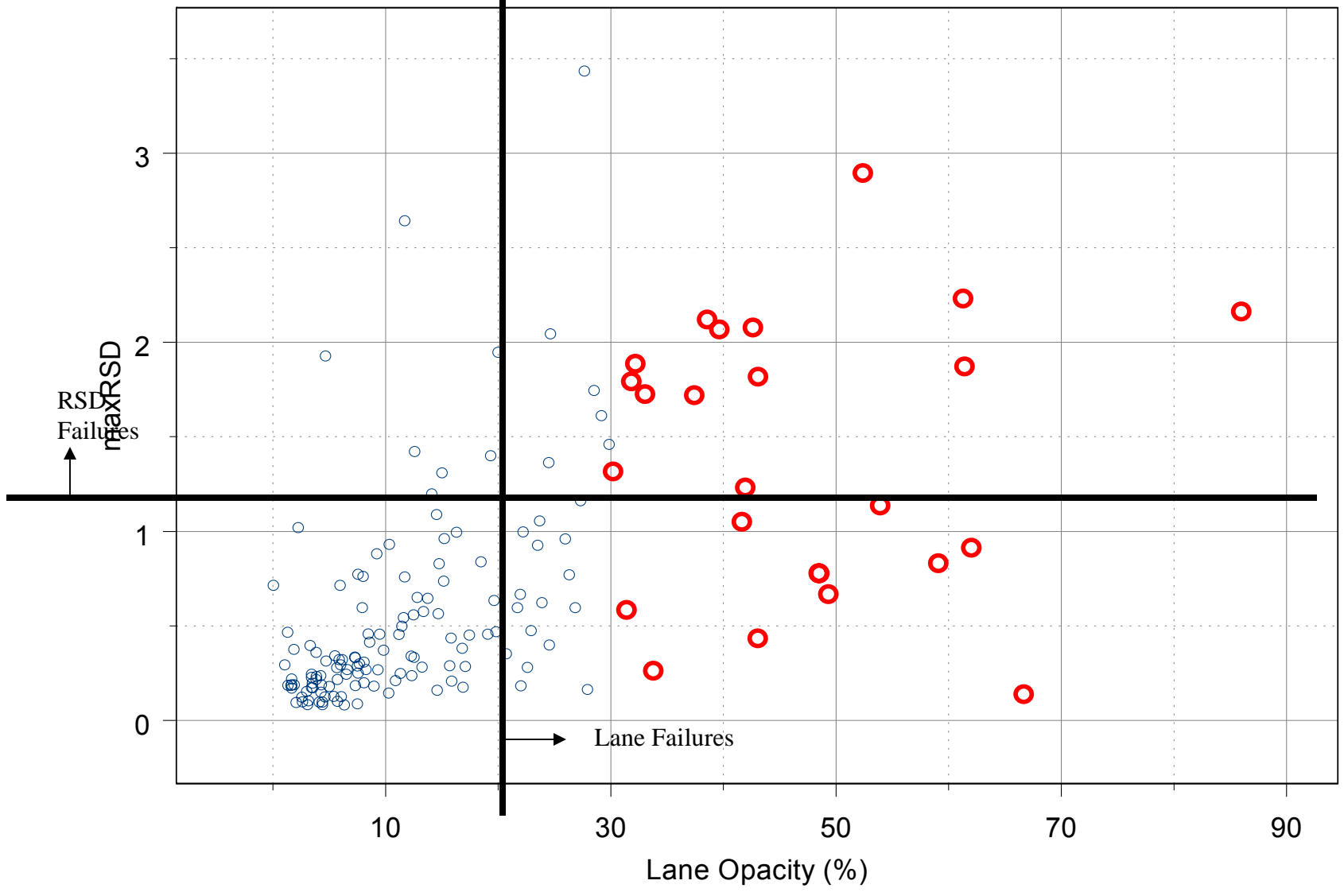
# Test Results Overview

- 156 Test Comparisons
- Scatter Diagram Format
  - Results with lane readings  $>30\%$  are highlighted on scatter diagram.





# maxRSD Reading vs Lane Opacity





# Summary Statistics

- 156 Comparison Tests
- Assuming Lane Opacity Failures ( $OP > 30$ )
- Assuming RSD Failure as ( $SF > 1.0$ )
  - Total of 25 Lane Failures
  - Total of 32 RSD Failures
  - Total of 16 common failures
  - 9 Lane failures not common to RSD
  - 16 RSD failures not common to Lane



## Questions/Follow-up Analysis

- 16 RSD “failures” did not show up as Lane “failures”.  
Why?
  - Were these vehicles smoking? Were there instrumentation problems?
  - Other explanations?
- 9 Lane “failures” did not show up as RSD “failures”.  
Why?



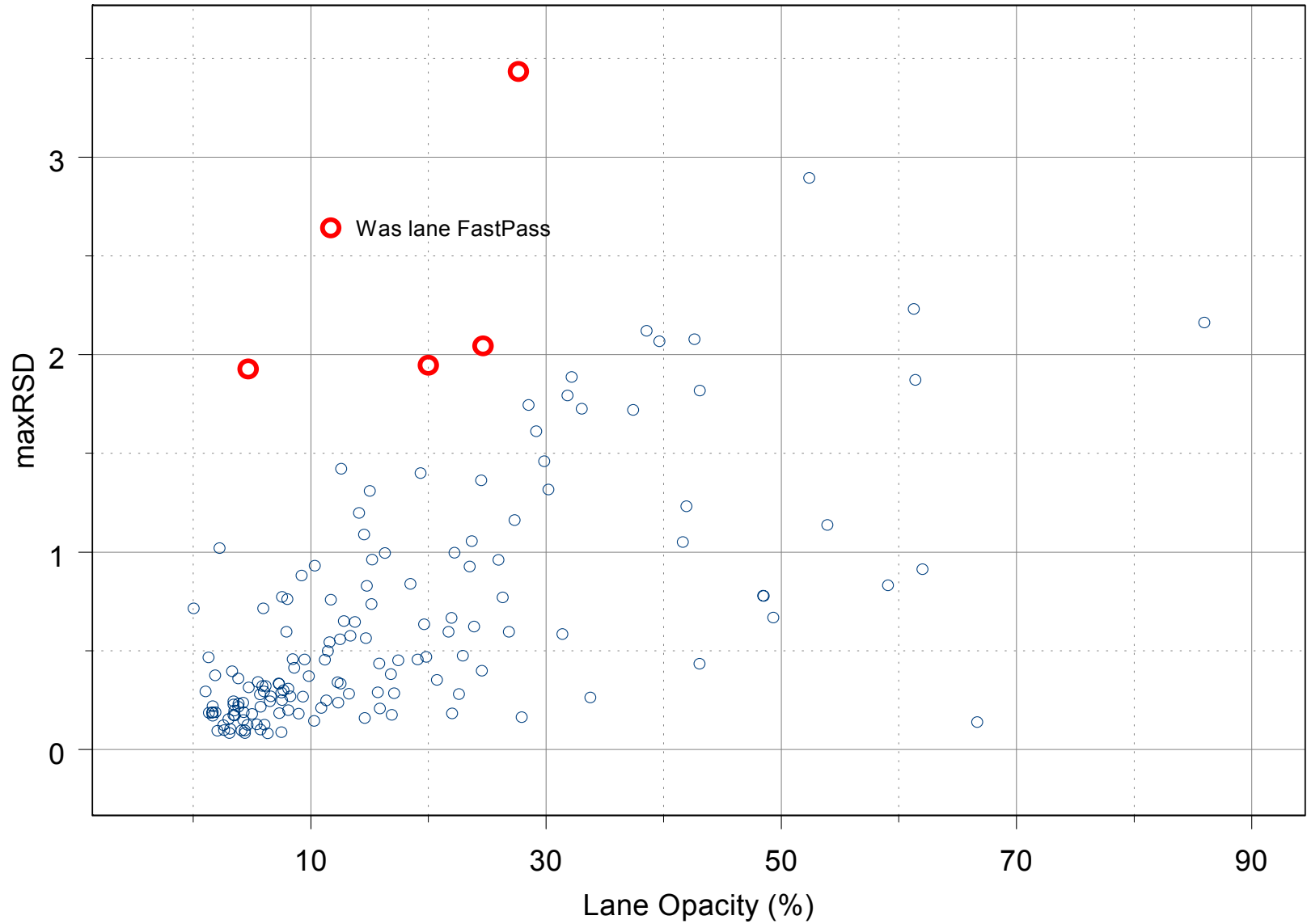
## 16 RSD “Failures” NOT Common to Lane High Readings

92

- Several of highest RSD test failures that are lane passes are highlighted.
- Were they really smoking vehicles? **Yes**, they were generally “visible to eye” smoking vehicles. See following pictures.



# max RSD Reading vs Lane Opacity





# RSD Failure/Lane Failure



20020530 bclang00160.jpg

0.000 0.000 x 0.44 14.71 797.2 294.58 1.8186 95.92 32.0

CO CO2 HC NO



# RSD Failure/Lane Failure





# RSD Failure/Lane Failure







# RSD Failure/Lane Failure





## High RSD Low Lane Results

- Since the RSD readings are high because vehicles are truly “smoking” (evidence is the pictures), the questions then become –
  - Why doesn’t the lane test reveal the high smoke content?
  - Do the RSD tests exceed the engine/vehicle power levels of the lane test?
  - Are there other factors such as oil-based “blue smoke”?
  - Was the lane test designed to reveal all smoking vehicles?



# Hypotheses

## High Lane Low RSD Results

- Basic Assumption is that an engine condition is realized in the lane that does not occur during drive-bys.
- Some evidence exists that lane test failures that occur in the initial acceleration period (start of test cycle) can be caused by late shifting (accelerating in 1<sup>st</sup> gear thereby over-speeding the engine).
- At least one test failed at the lane, passed very clean through several RSD passes, was retested in the lane starting in 2<sup>nd</sup> gear, and passed cleanly.
- Lane failures occurring on the 2<sup>nd</sup> acceleration phase of the test cycle are at speeds higher than could be produced at the RSD site.



# Conclusions

- Both RSD and IM147 Opacity Test identify high smoke emitters.
- RSD tests identified more high smoke emitters than did the lane test.
  - Lane: 25
  - RSD: 32
  - Common: 16
- Additional RSD high smoke emitters are generally confirmed by visual evidence.
- Additional investigation is required to determine testing differences.

[Back to Performance Summary](#)

# Matching Fleet Emissions

## 1. MBTA Bus Monitoring and Control Program



August 04



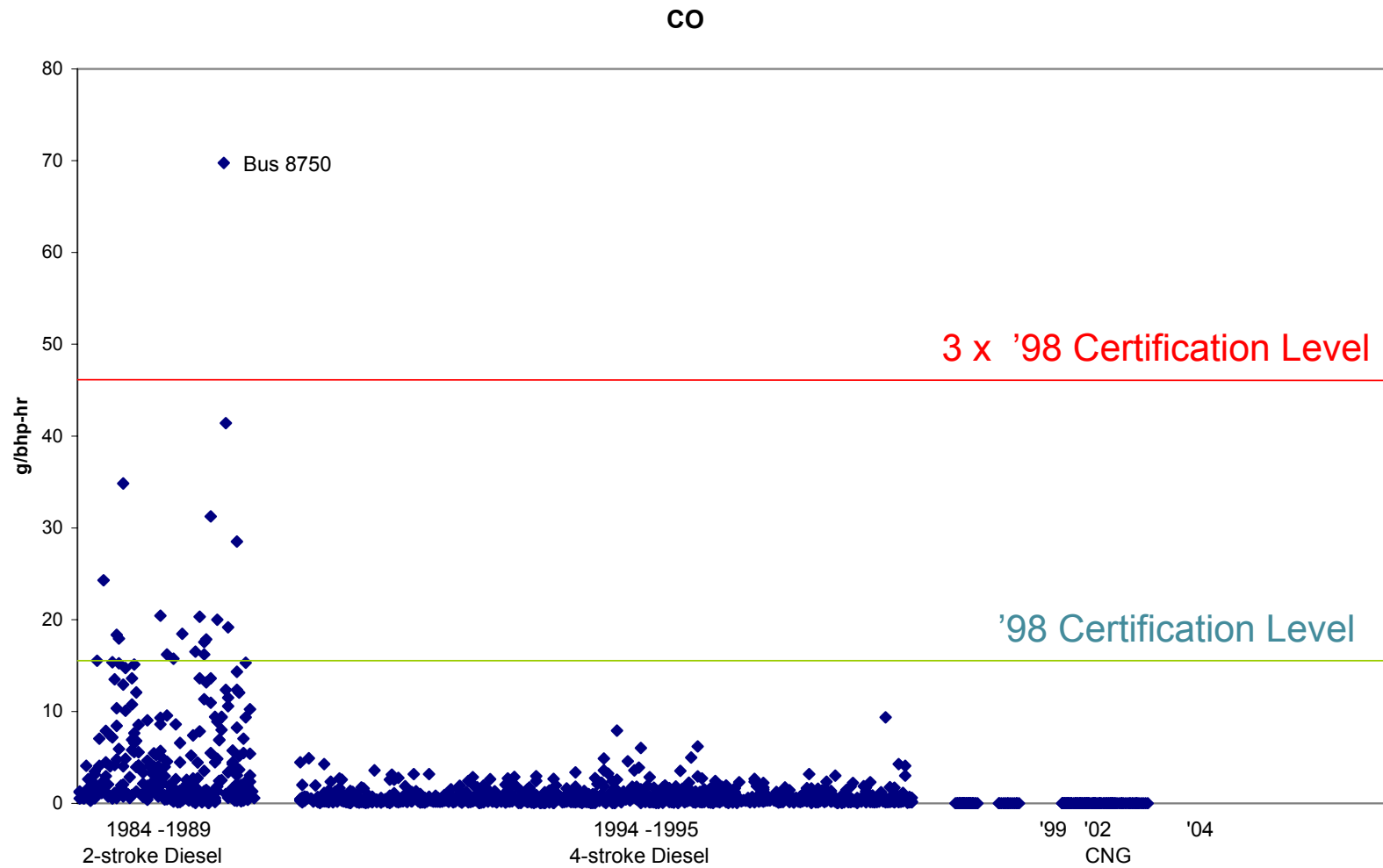


# MBTA Transit Fleet Screening

- Approximately 400 buses screened over a two-week period, with multiple data points per bus (approx 1,500 total)
  - ‘84-’89 two-stroke diesel 80 buses
  - ‘94-’95 diesel (98 spec rebuilds) 280 buses
  - ‘99 CNG (40’ transit) 11 buses
  - ‘02 CNG (60’ artic) 10 buses
  - ‘04 CNG (40’ transit) 40 buses



# CO Data





## CO Lessons Learned

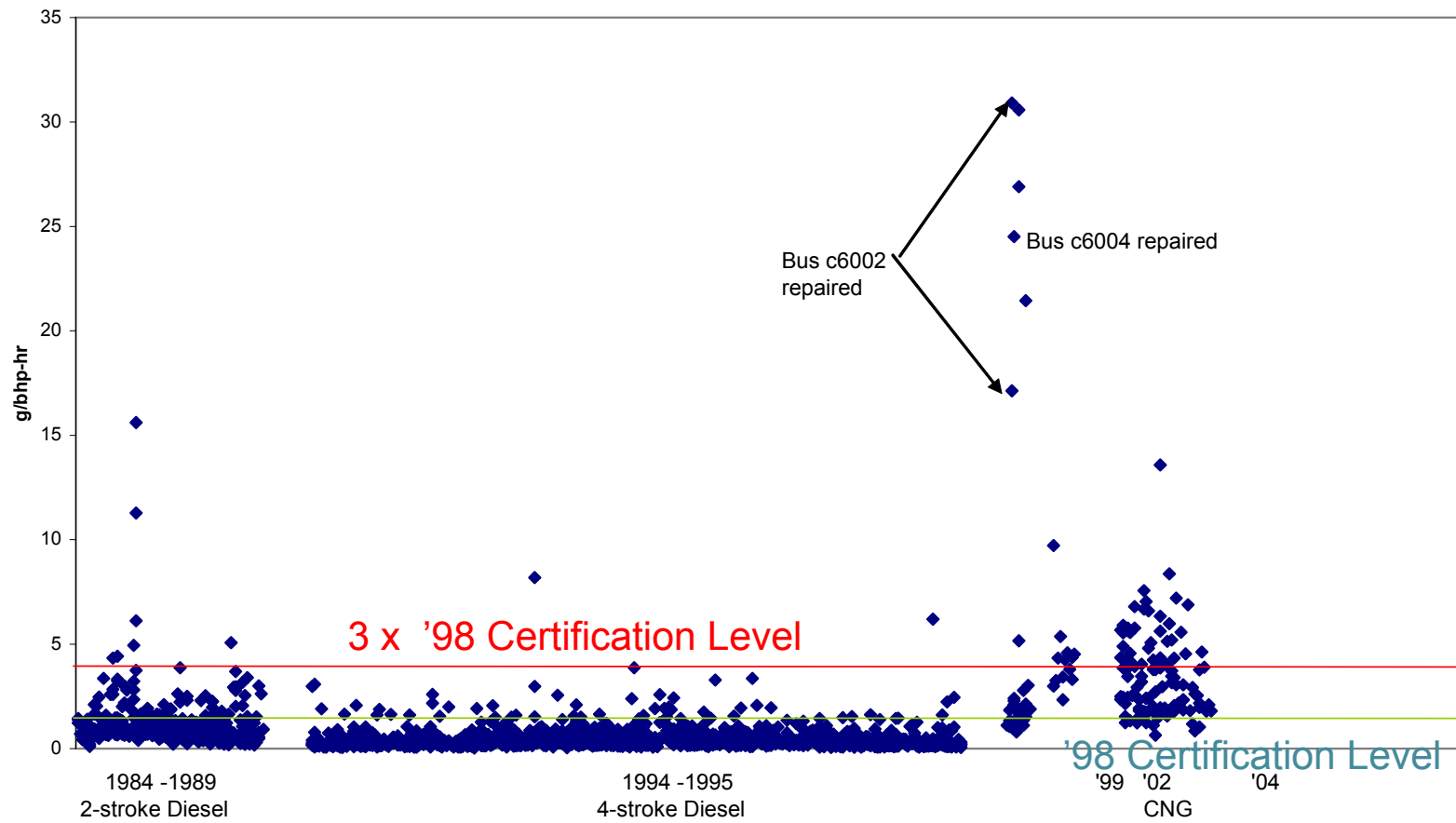
- CO tracks as expected for all buses
  - Older two-stroke buses
    - One possible outlier in need of repair
    - Same bus flagged later from Smoke data
  - All remaining buses in fleet well within engine certification standard





# HC Data

## HC





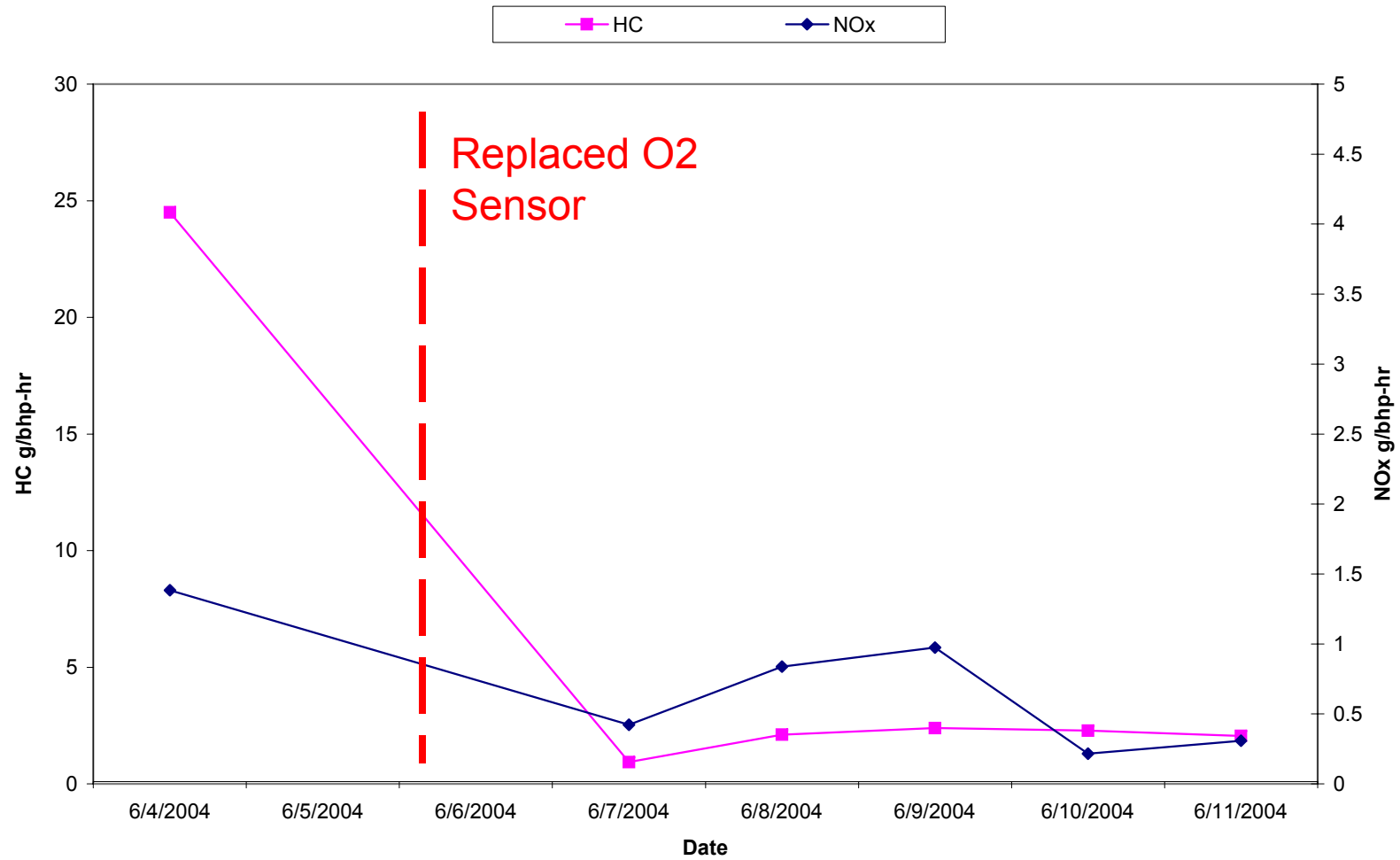
## HC Lessons Learned

- Diesel two-stroke and four-stroke as expected, with low nominal HC levels
- CNG buses (specifically '99 vintage)
  - Exhibiting lean NO<sub>x</sub> misfire and excess methane emission levels
  - O<sub>2</sub> sensor repairs for several buses show that HC was significantly reduced, with some added NO<sub>x</sub> benefit
- HC may be a viable surrogate for CNG I/M



# Effect of Maintenance

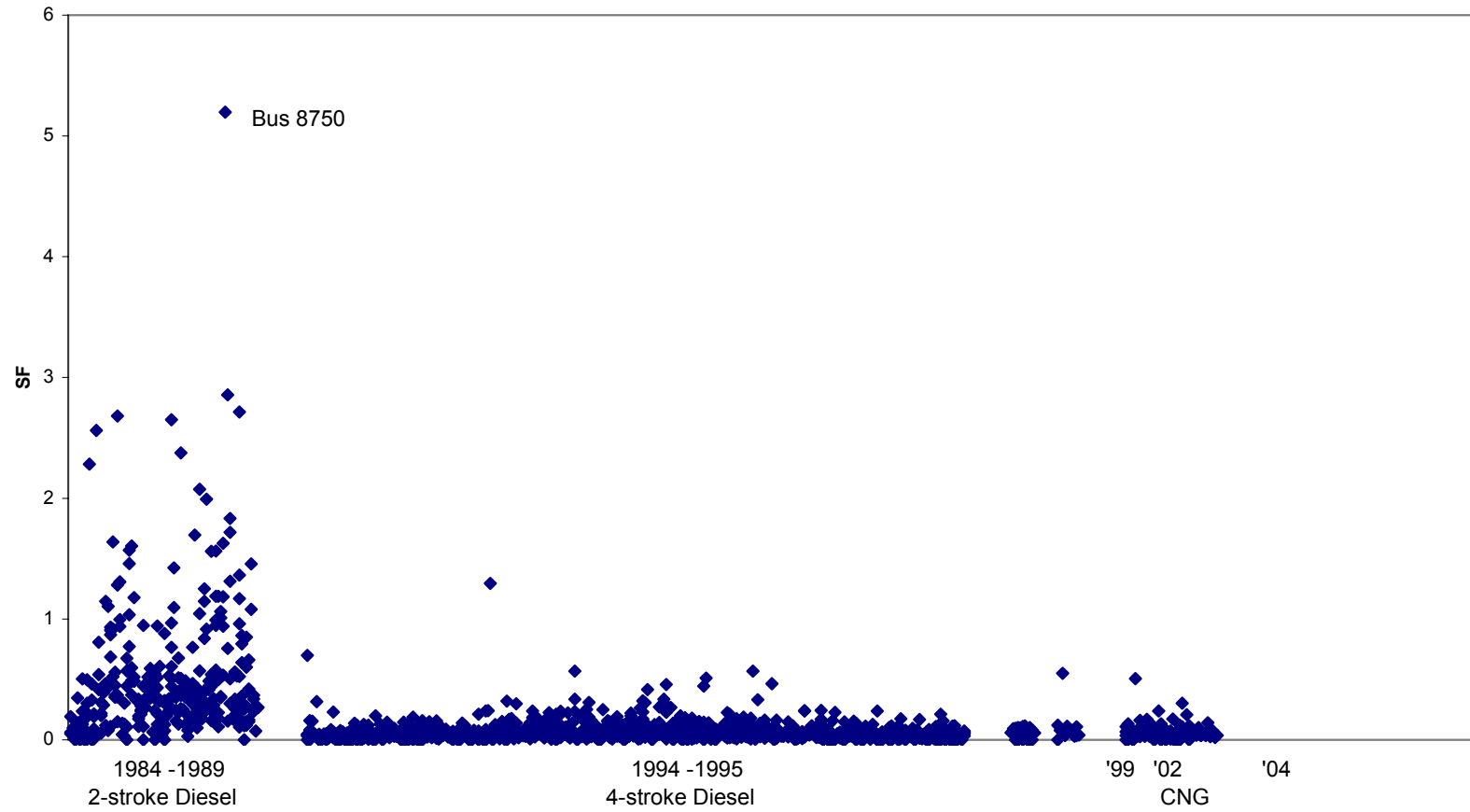
Bus 6004 Repair Results





# Smoke Data

Smoke



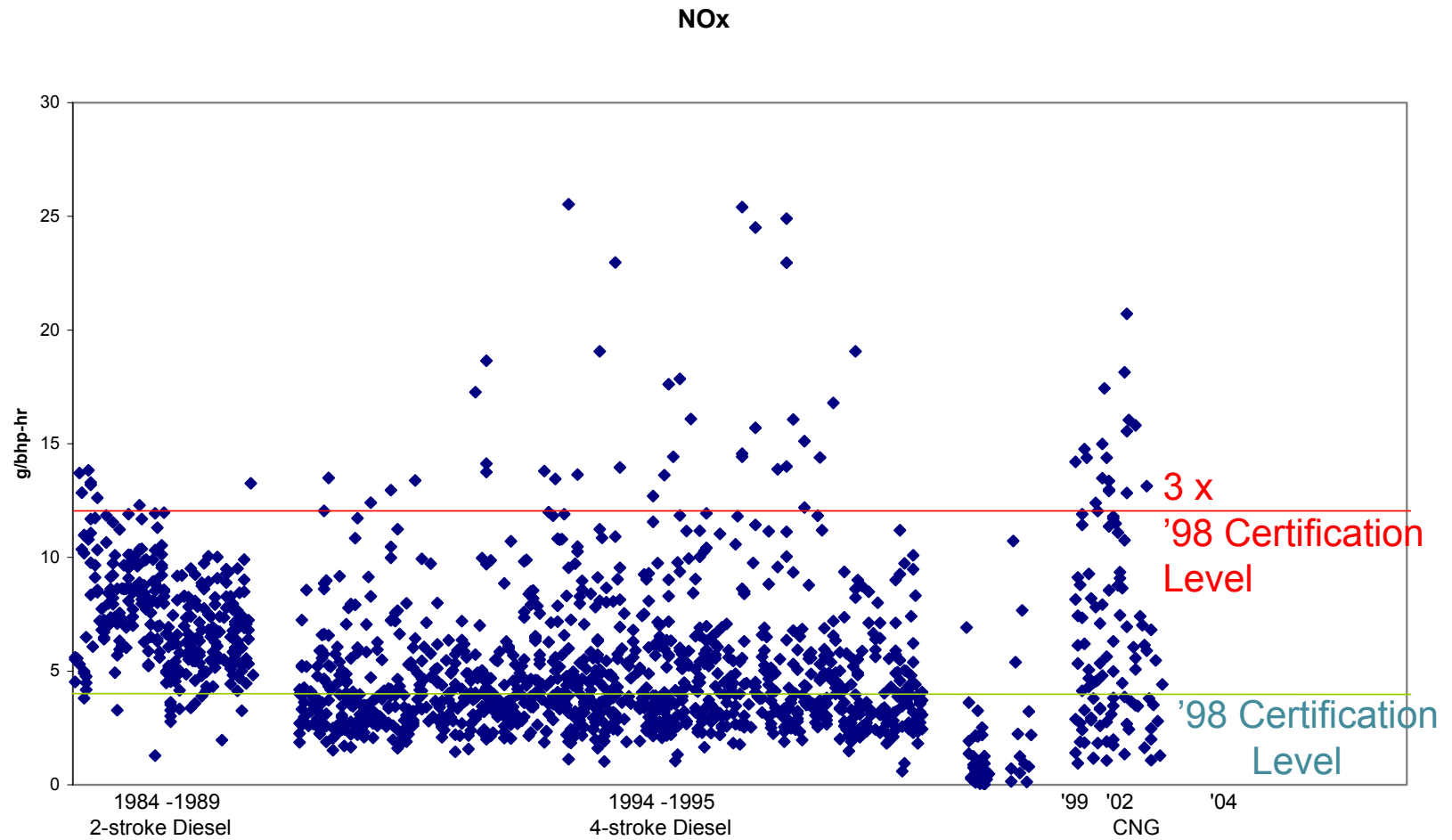


# Smoke Lessons Learned

- RSD unit uses UV for smoke factor determination
- Results as expected, with DPF-equipped 4-strokes and CNG showing very low smoke, and two-stroke buses higher
  - 2-stroke Bus 8750 flagged for further analysis, OBD scan and Opacimeter test. No failure determination yet for this bus
  - The few outliers in '94-'95 bus group will have DPF modules inspected for damage



# NOx Data



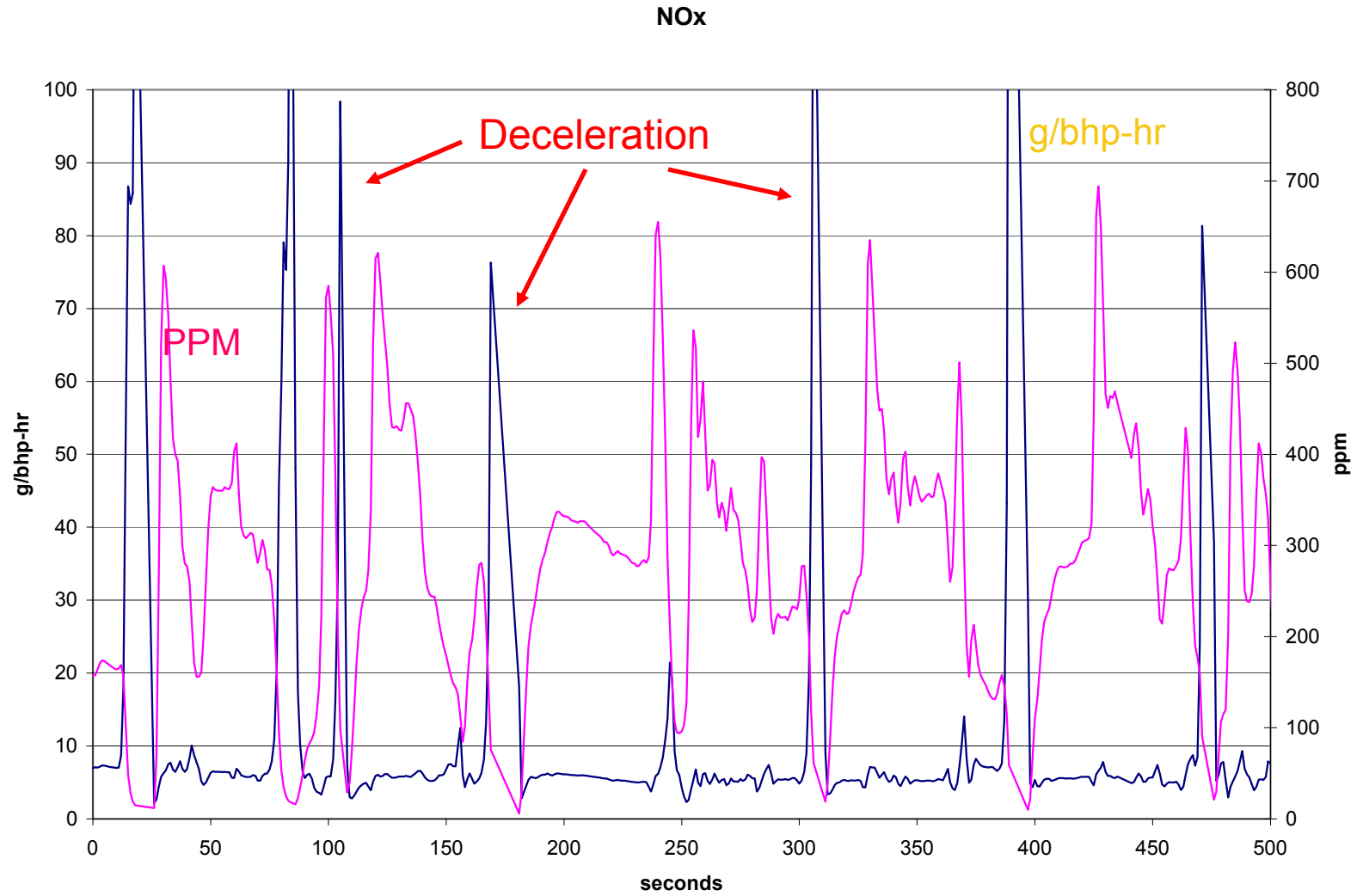


# NOx Lessons Learned

- NOx measurements appear accurate, with weight of readings for each bus type at or near the certification standard for that engine
  - 2-stroke buses show higher NOx than 4-stroke buses
  - Ultra low NOx of '99 CNG buses typical of lean misfire O2 sensor failure (see HC data)
  - '04 CNG NOx similar to diesel, with greater variability
  
- Some of the high NOx readings on 4-stroke diesel and '04 CNG appear to be artifact of test method
  - See PEMS data for NOx, which illustrates spike in NOx gm/bhp-hr upon deceleration
  - Illustrates need for more control over bus mode during sampling



# NOx PEMs Data







# Initial Results Over-all

- Over 1500 readings for ~400 buses over a two-week period
  - Data collection is automated
  - Very little post-processing required
- Demonstrated accuracy and ease of use with RSD equipment makes it useful for I/M screening and emissions inventory data collection
  - Can rapidly screen entire fleet(s)
  - Can flag outliers for maintenance action
  - Can demonstrate effectiveness of maintenance action on individual vehicles
- More control of vehicle mode needed during data collection
  - In general want to collect data during vehicle acceleration
  - For permanent I/M programs, can control with physical installation of equipment and/or procedures/training
  - For road-side data collection programs, need to choose collection site carefully
  - Could also be facilitated with more exact vehicle speed sensing



## Next Steps (on MBTA Project)

- Use PEMs and Chase Measurements to get detailed emission signature for each bus type
  - Determine whether 2-stroke diesel and CNG show same NO<sub>x</sub> spikes on deceleration that would flag false failures
  
- Further evaluate effect of maintenance action on outlier results (2-stroke, CNG)
  
- Determine best indicator for I/M by engine type
  - 4-stroke diesel: NO<sub>x</sub>
  - CNG: HC
  - 2-stroke diesel: Smoke or CO?

# Matching Fleet Emissions

## 2. EPA RSD Cross-Border Development Program



August 04





# Cross Border Phases

Phase 1	3 Weeks	2004
<i>Goal: Fleet Baseline &amp; RSD Correlation</i>		
Phase 2	9 Months	2005
<i>Goal: Screening Application Development</i>		
Phase 3	On-going	2006
<i>Goal: Enforcement Demonstration Program</i>		



# Cross-border Pilot

## Phase 1

- Location: Nogales, Arizona
- Sponsors: USEPA, ADOT, ADEQ, ESP
- Duration: Phase 1, 3-weeks
- Timetable: Oct./Nov. 2004
- Goals:
1. Fleet Characterization (baseline)
  2. Test Comparison (RSD, PEMS, Chase)



# Portable Emissions Analyzer "Correlation"

## In-Use Testing:

- Recruit Vehicle
- Install Analyzer
- Trace a Few Miles
- Remove Analyzer





# Mobile Chase Laboratory

## “Correlation”

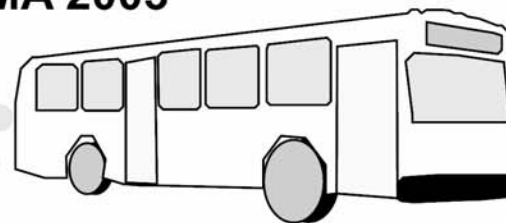
### Chasing the Polluters

Researchers used a van equipped as a mobile laboratory to collect pollution data in the streets of Mexico City



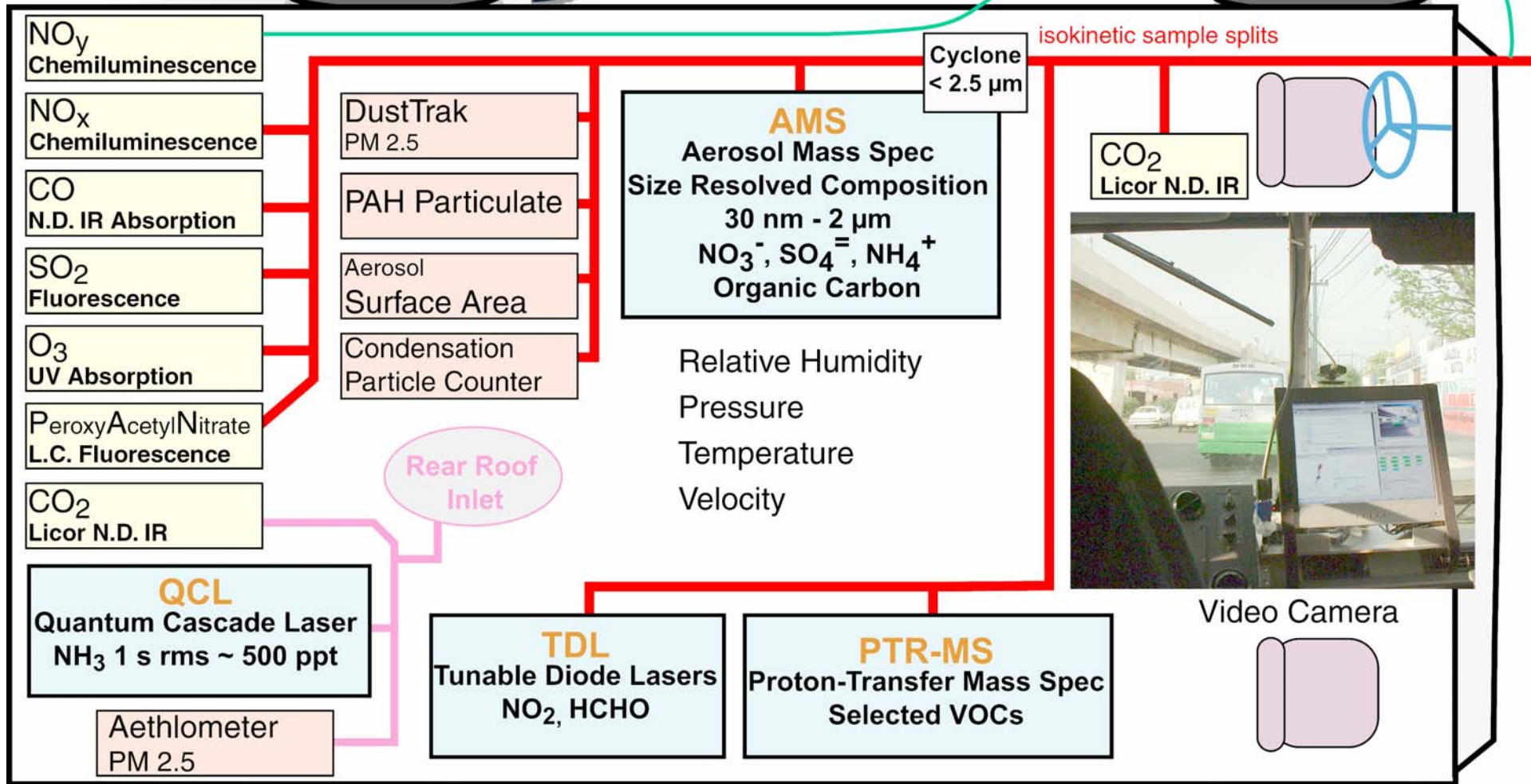


# Aerodyne Mobile Lab MCMA 2003



**Roof**  
Sun Photometer  
Anemometer  
GPS

NO<sub>y</sub> converter







# Performance Summary

What it took to get where we are...for LDGVs.

- Technology (HW & SW) – Ready [NH<sub>3</sub>, Cold, Unmanned]
- Matching Laboratory Analyzers - Done
- Matching Inspection Results - Done
- Matching Fleet Emissions – Done

What it will take to get where we want to go...for DVs.

1. Technology (HW & SW) – SF Ready [NO<sub>2</sub>, SO<sub>2</sub> Begun]
2. Matching Laboratory Analyzers - NO done [SF Begun]
3. Matching Inspection Results – NO done [SF ?]
4. Matching Fleet Emissions - ? [MBTA Begun, EPA Pending]